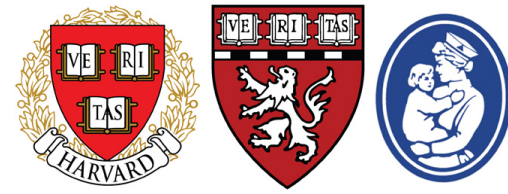


Visual recognition: peeking inside computations in the brain



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Camille Gomez



Richard Born



Jojo Nassi



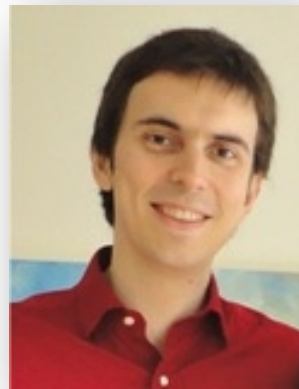
Laura Groomes



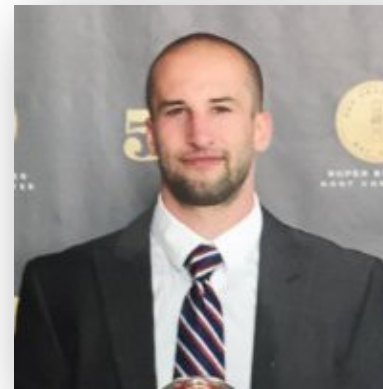
Hanlin Tang



Thomas Miconi



Bill Lotter



David Cox



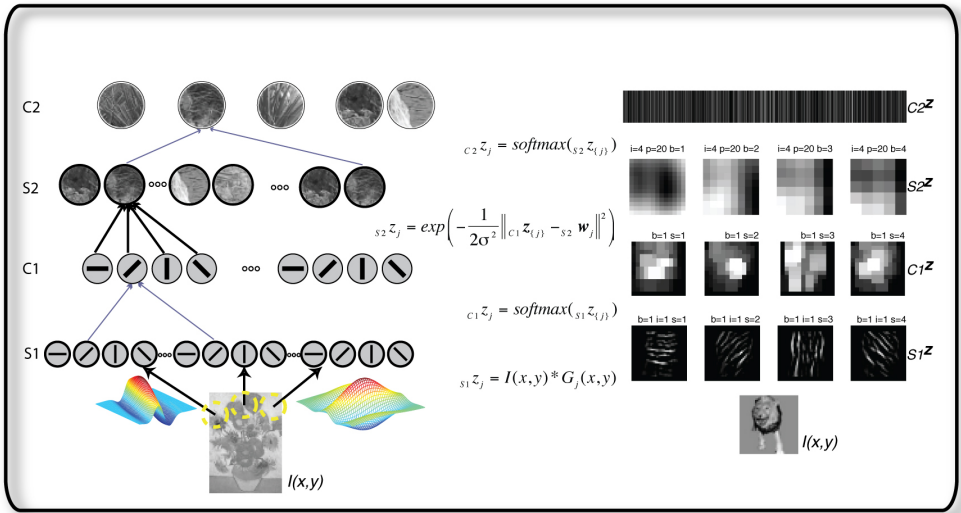
Biologically-inspired computations are powerful

Over millions of years of evolution, “interesting” solutions to difficult problems have emerged through changes in neuronal circuits

- Hardware and software that work for many decades
- Parallel computation (with serial bottlenecks)
- Reprogrammable architecture
- Low power
- Single-shot learning
- “Discover” structure in data
- Fault tolerance
- Robustness to sensory transformations
- Component interaction and integration of sensory modalities

Algorithms,
solutions

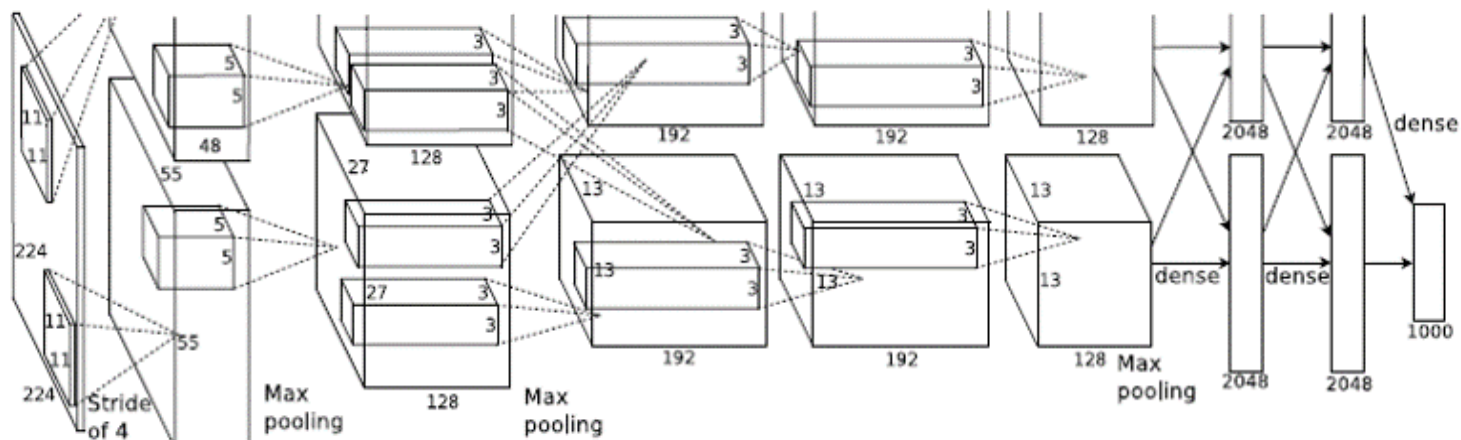
Bottom-up models of object recognition



Fukushima, Mel,
Olshausen, LeCun,
Riesenhuber, Rolls,
DiCarlo, ...

Serre et al 2007

Deep convolutional networks



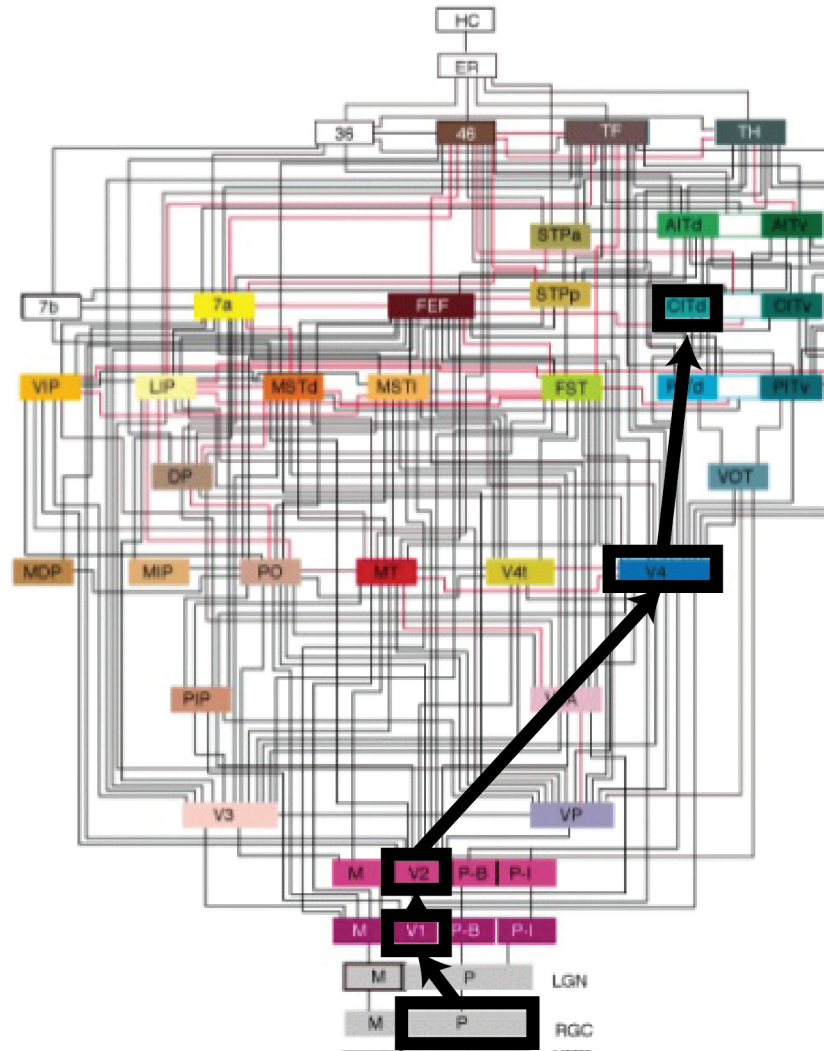
Krizhevsky et al, NIPS 2012

There is more. Much more.

A schematic diagram
of visual cortex
connections in
macaque monkeys

This is a major
oversimplification ...

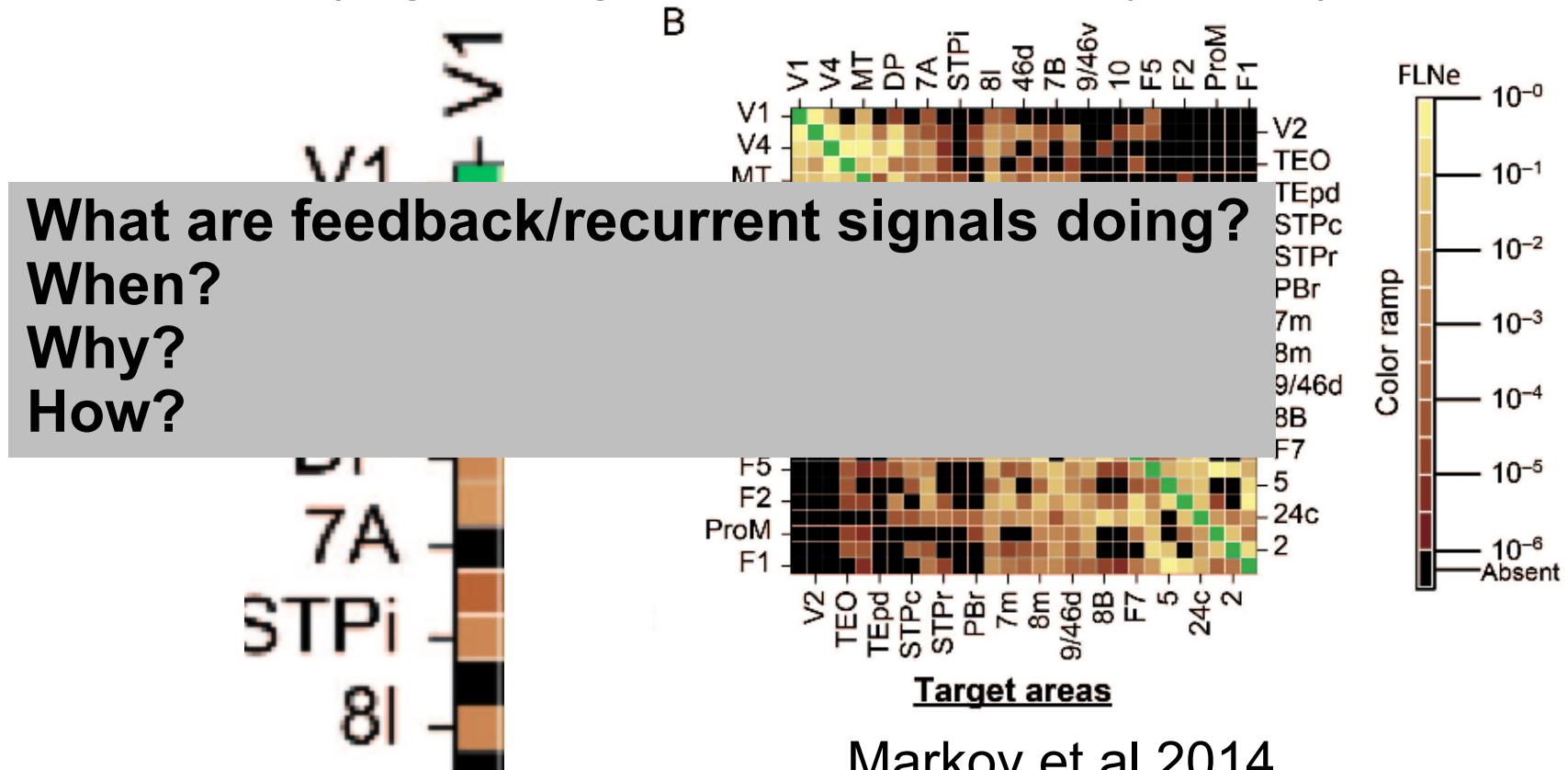
Each box contains a
bewildering and
magnificent world of
computations



Felleman and Van Essen 1991

Why are there so many feedback and recurrent connections?

There are more horizontal + top-down projections than bottom-up ones (e.g. Douglas 2004, Callaway 2004)



Markov et al 2014

Computational roles of recurrent/feedback signals

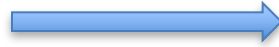
1. Pattern completion (recurrent computations)
2. Predictive coding (feedback computations)



Image by Hanlin Tang

Pattern completion as a hallmark of intelligence

A, C, E, G,



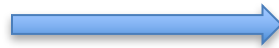
I

1, 2, 3, 5, 7, 11,



13

V-s-a R-c-g-i-i-n



Visual Recognition

Even though it was raining heavily,
Jonathan decided to go out without
an



Umbrella



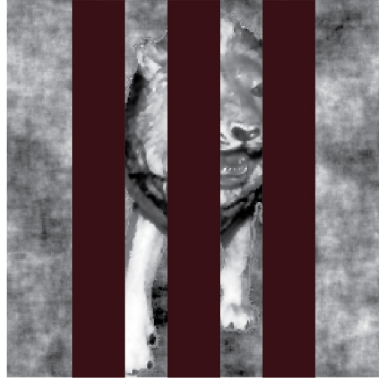
Also:
Other sensory modalities
Music
Social interactions

Objects can be recognized from partial information

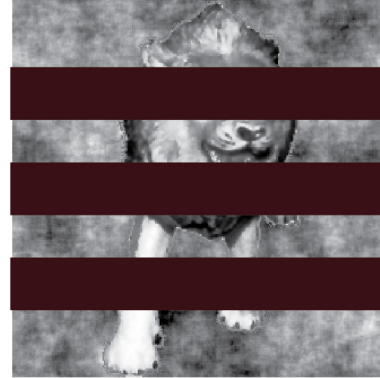
a



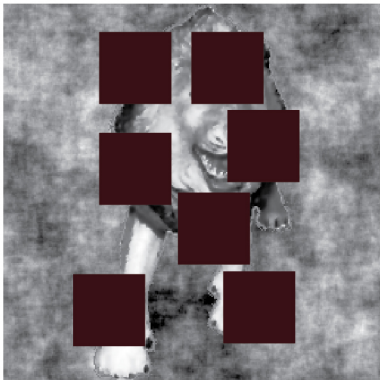
b



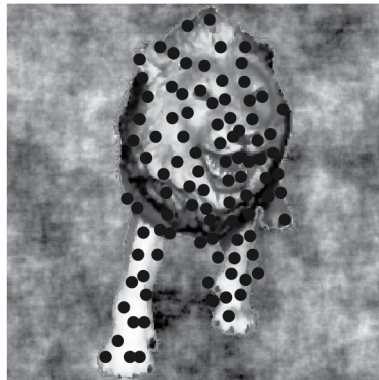
c



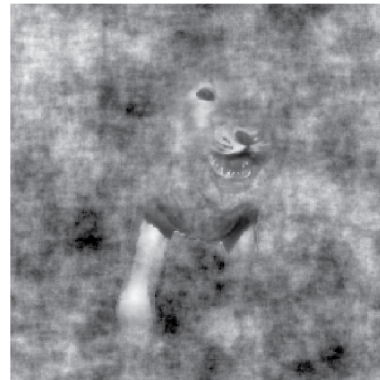
d



e



f



4 bubbles



Evaluating pattern completion

20 bubbles



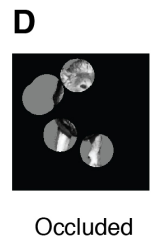
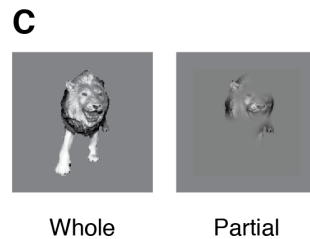
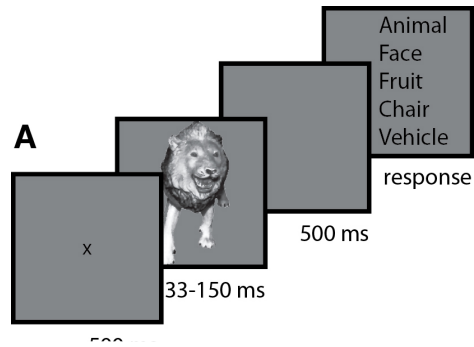
10 bubbles



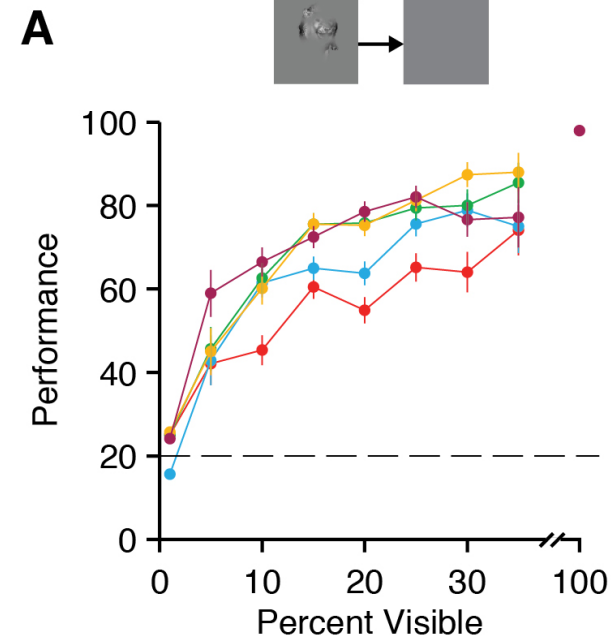
6 bubbles



4 bubbles

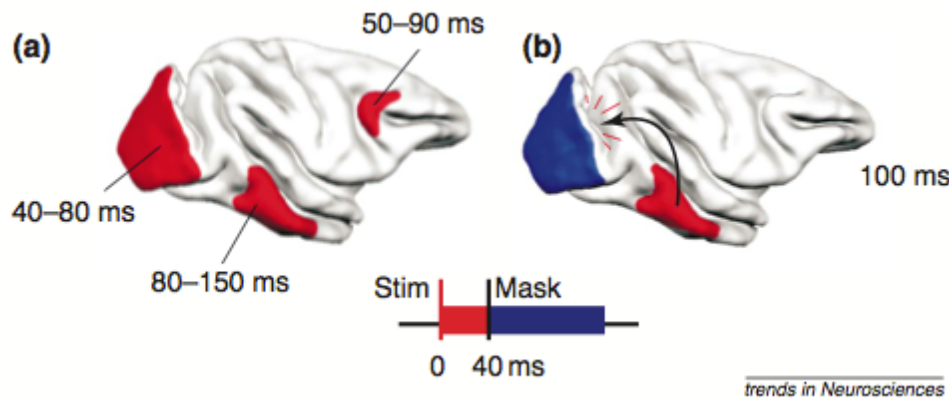


Strong robustness to limited visibility

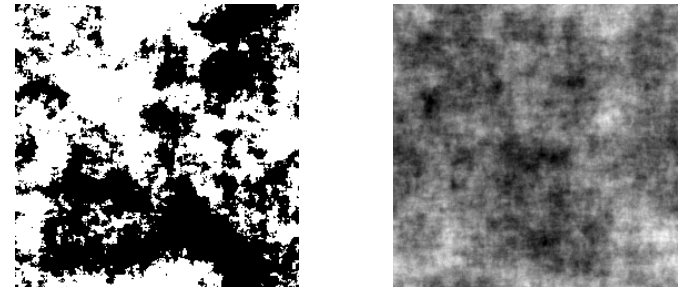


Backward masking interrupts processing (presumably of feedback/recurrent computations)

Models:



Masks:



Lamme V, Roelfsema P (2000)

- Short delays ($SOA < 20ms$): mask reduces visibility
- Longer delays: mask is purported to disrupt recurrent/top-down processing

V1: Bridgeman 1980, Maknik and Livingsstone 1998, Lamme et al 2002

IT: Kovacs et al 1995, Rolls et al 1999

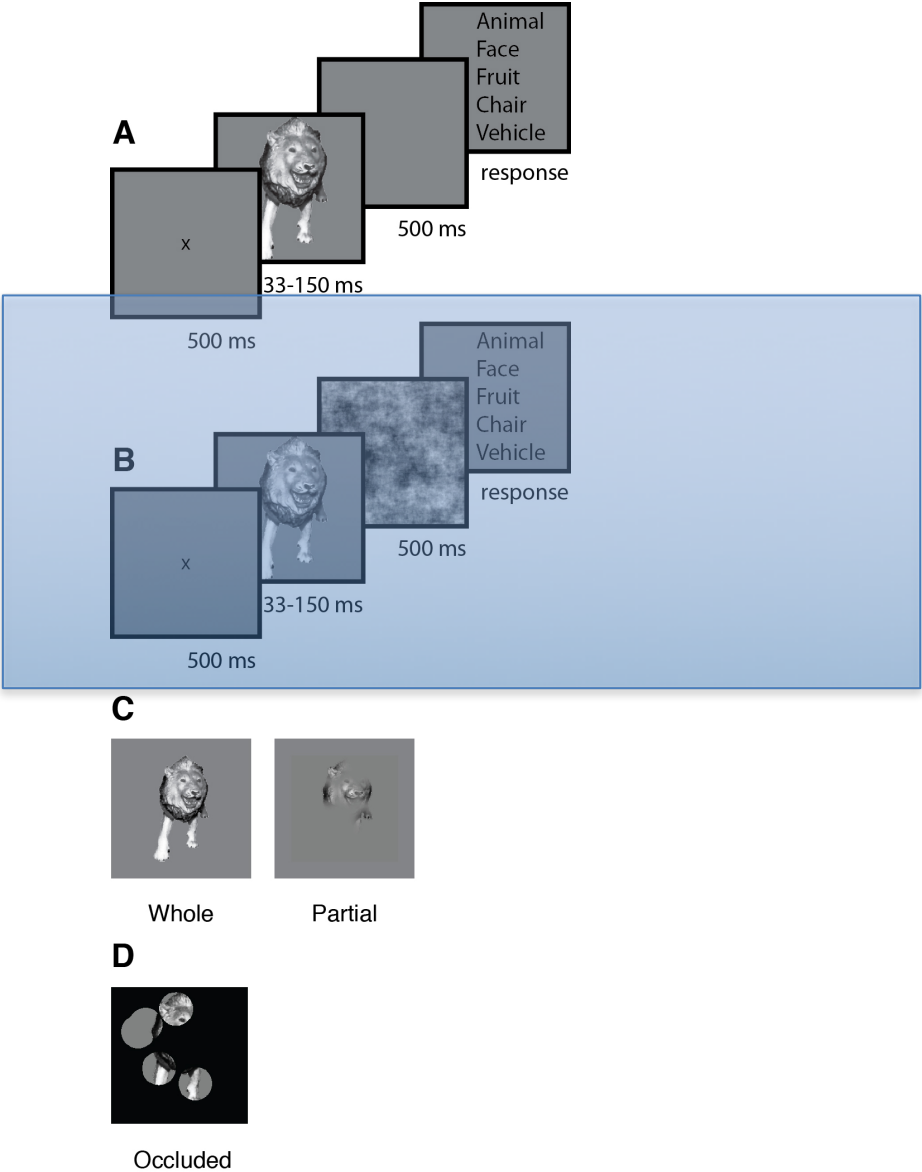
Evaluating pattern completion abilities

20 bubbles

10 bubbles

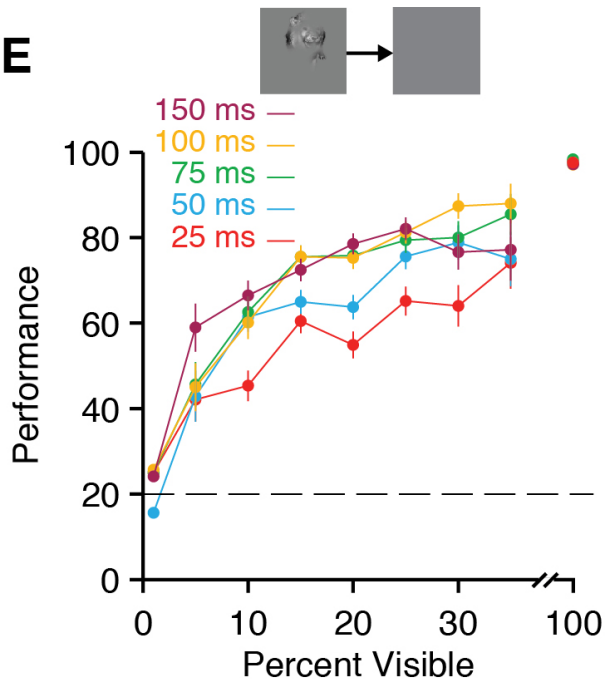
6 bubbles

4 bubbles

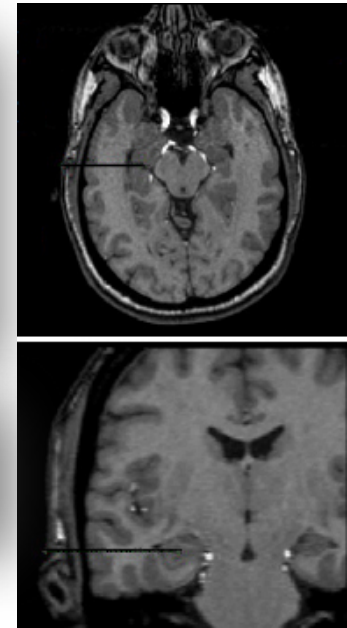
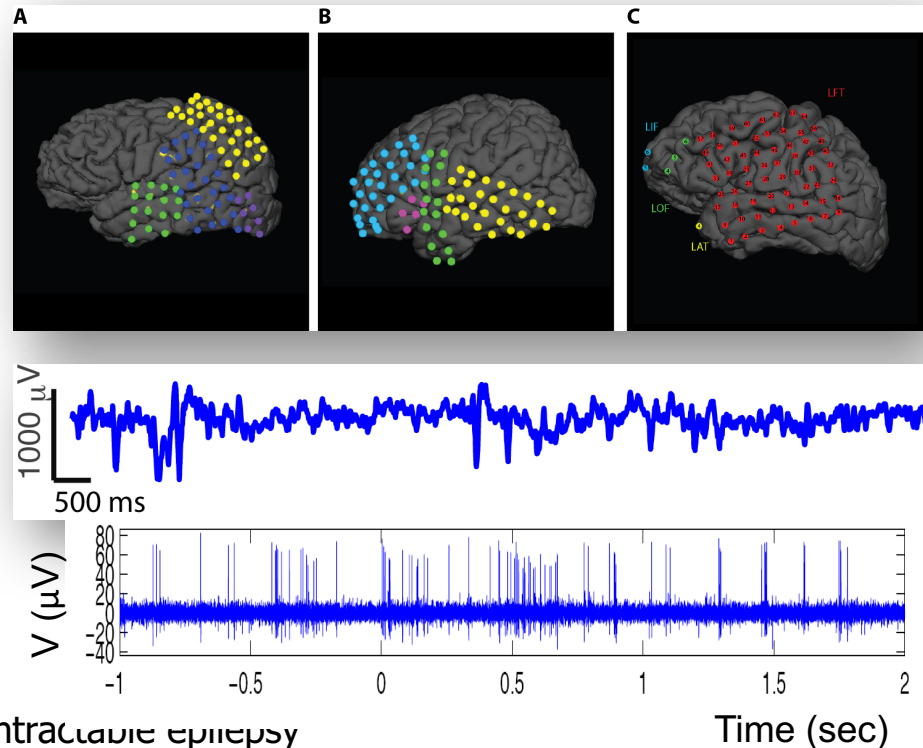
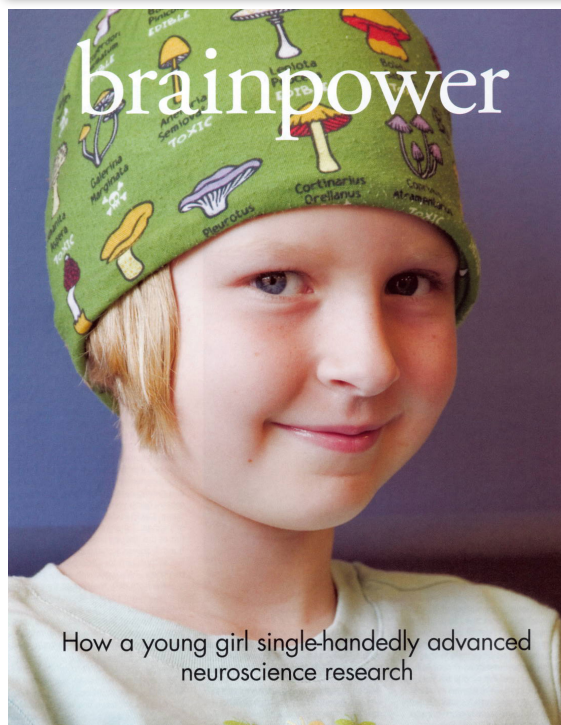


Backward masking disrupts pattern completion

E



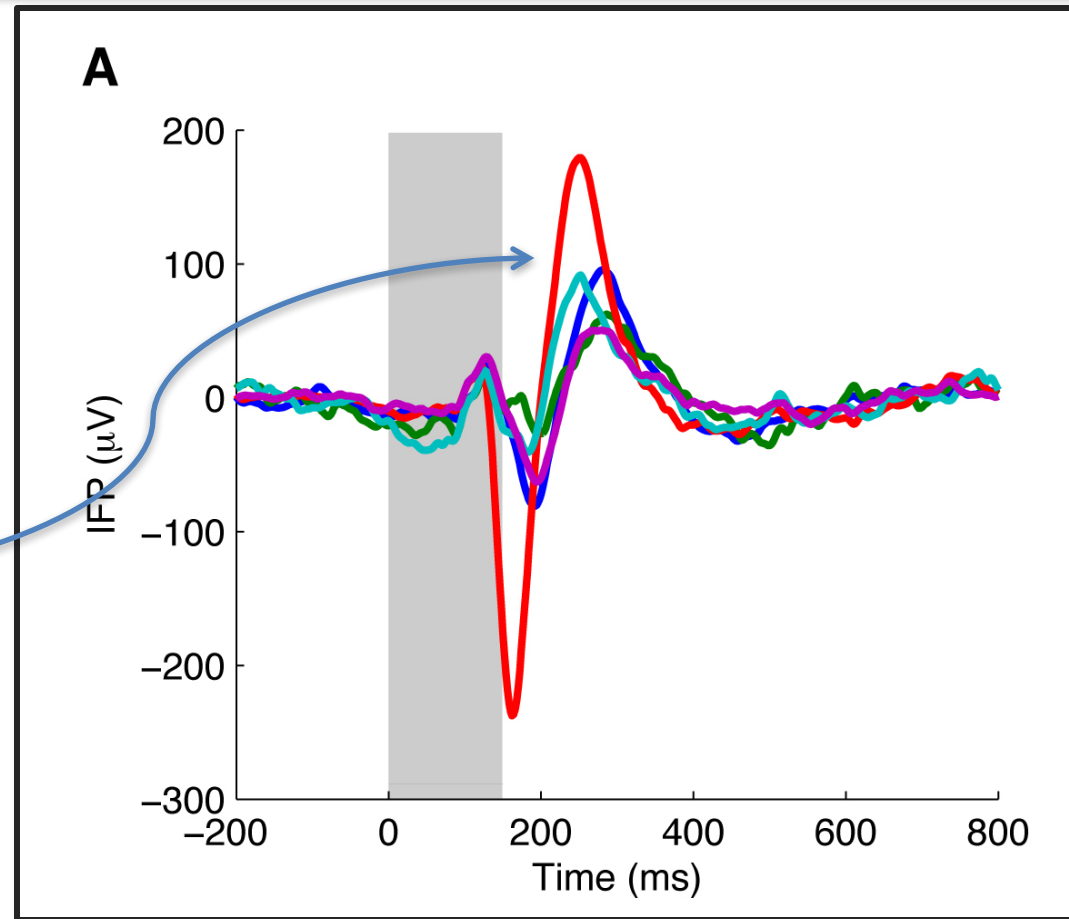
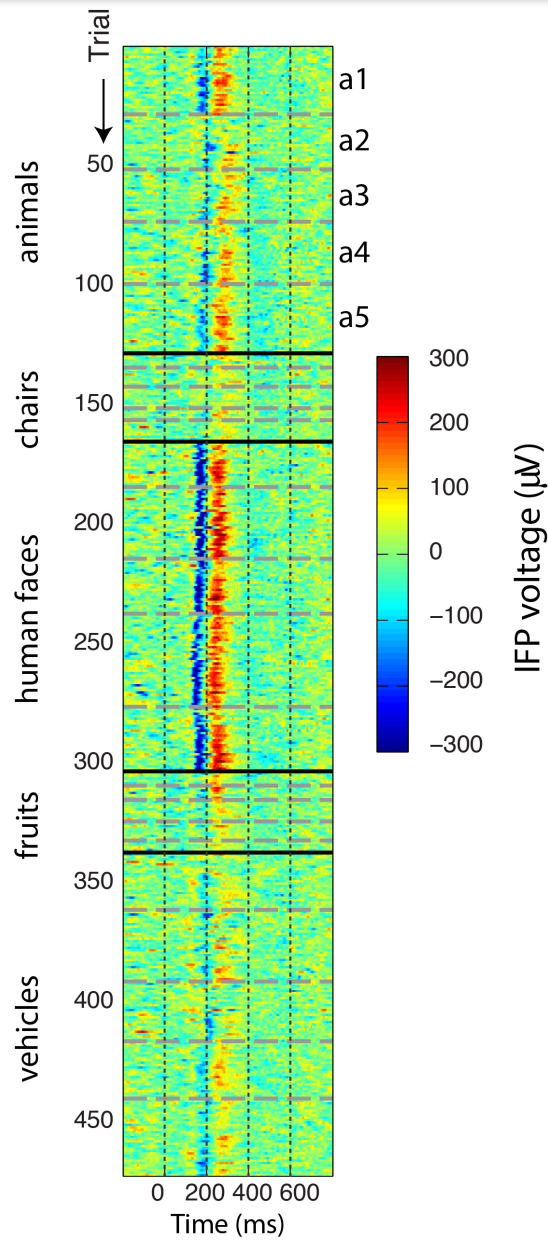
Peeking inside the human brain



- Patients with pharmacologically intractable epilepsy
- Multiple electrodes implanted to localize seizure focus
- Patients stay in the hospital for about 7-10 days
- All experiments are approved by the Institutional Review Boards
- All testing is performed with the subjects' consent

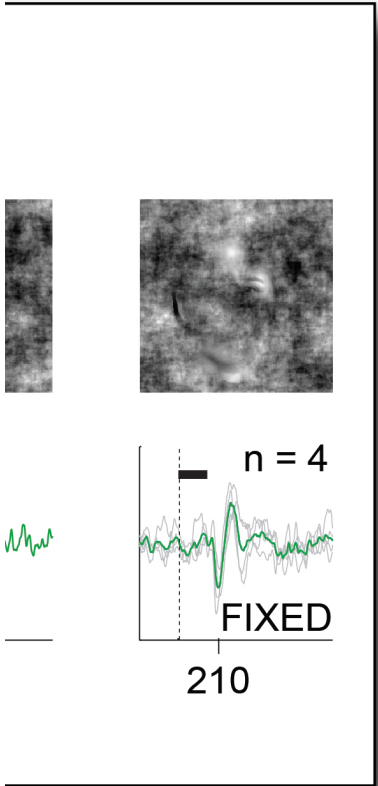
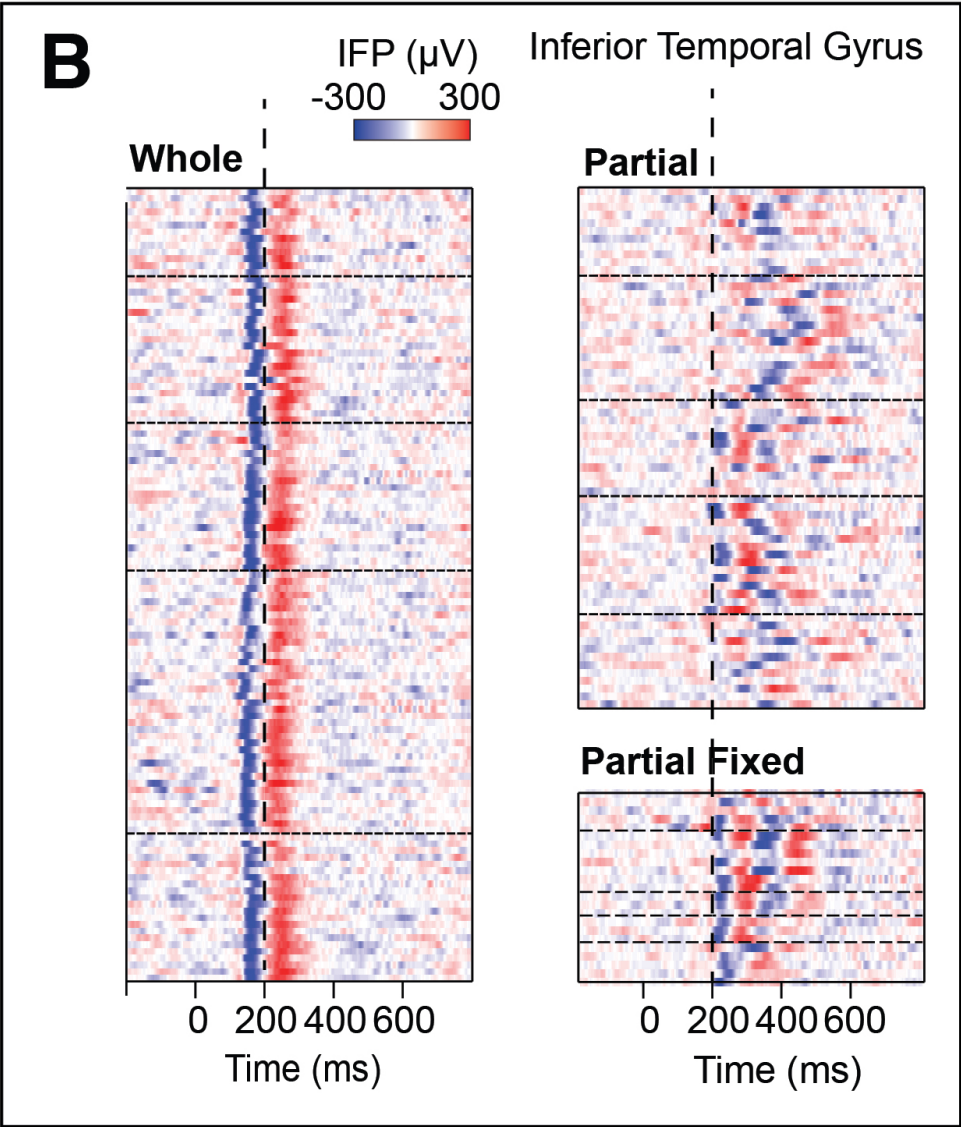
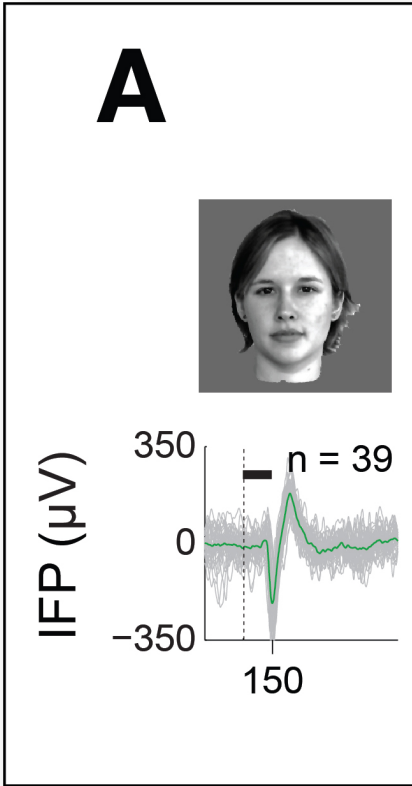
Neurosurgeons: **William Anderson, Joseph Madsen, Itzhak Fried**

Reliable, selective and rapid responses in human inferior temporal cortex

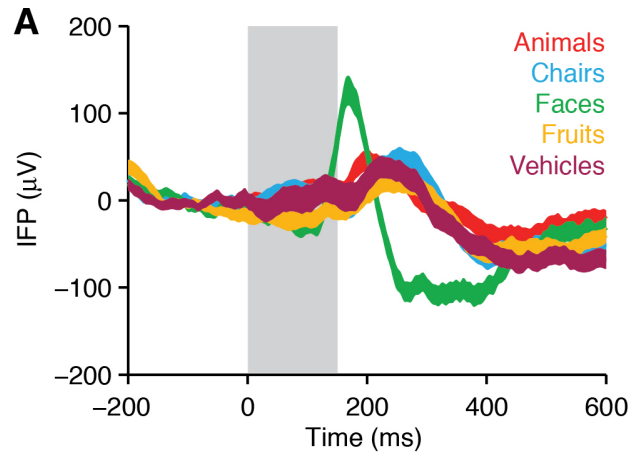


Inferior temporal gyrus

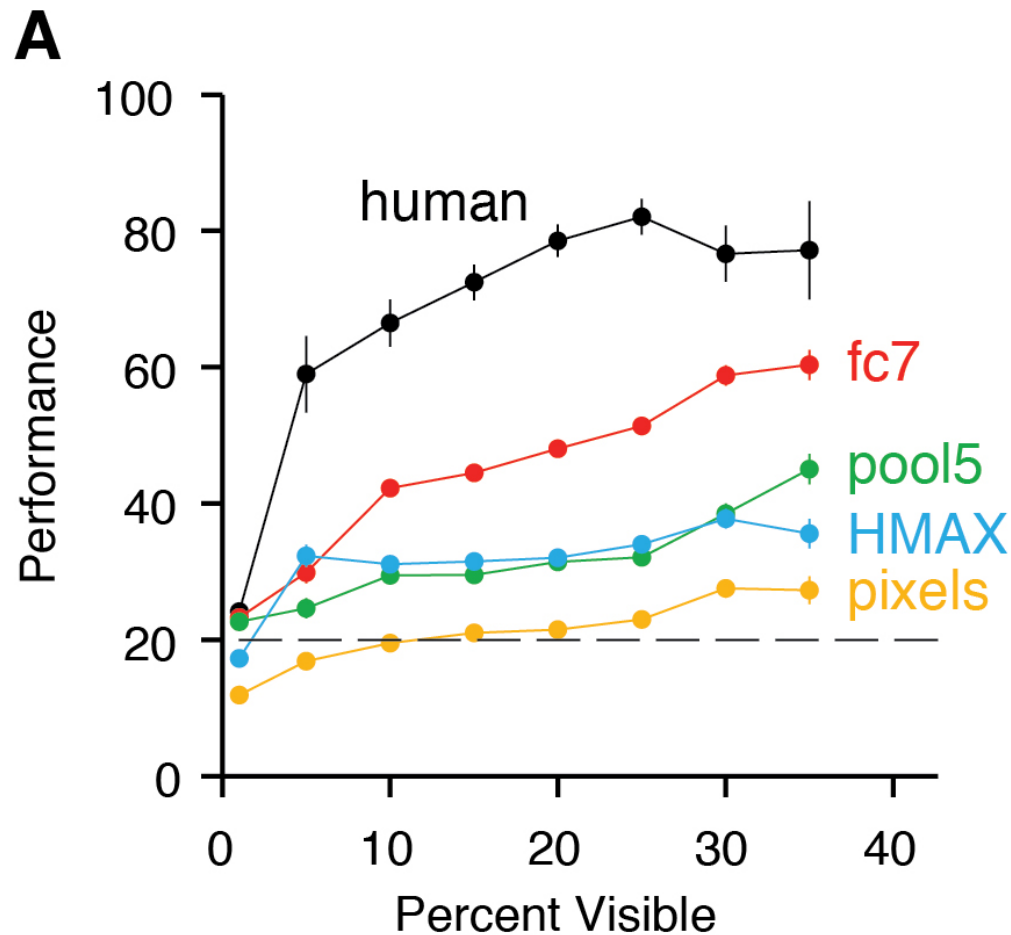
Example responses during object completion



The behavioral effect of masking correlated with the neural response latency on an image-by-image basis



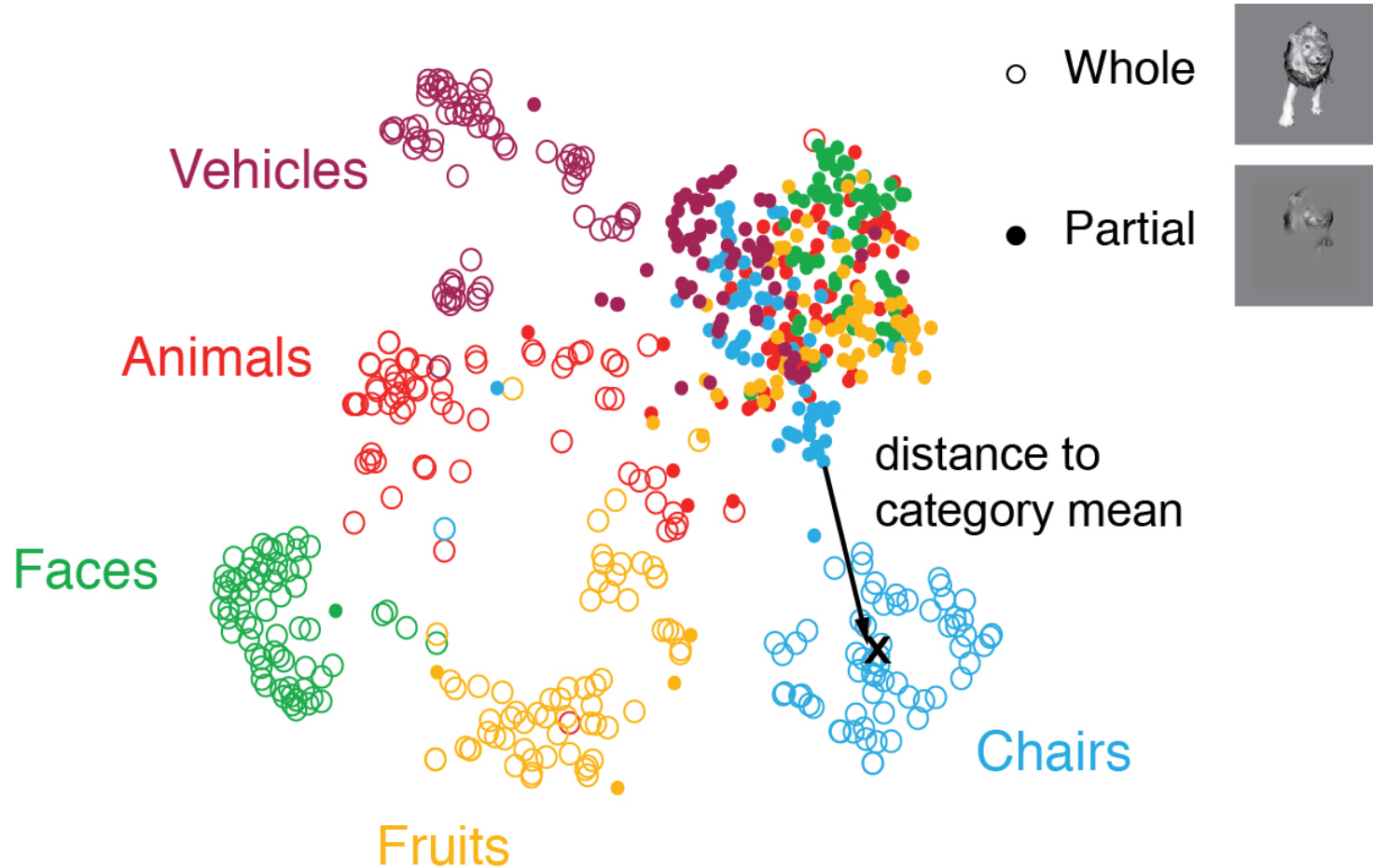
Bottom-up models significantly underperform in recognition of partial images



See also Pepik et al 2015, Wyatte et al 2012

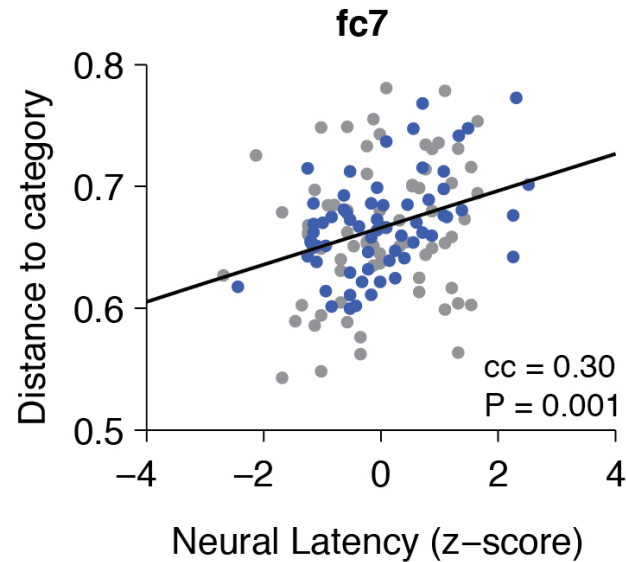
2D object representation at the top of the model hierarchy is not robust to occlusion

B

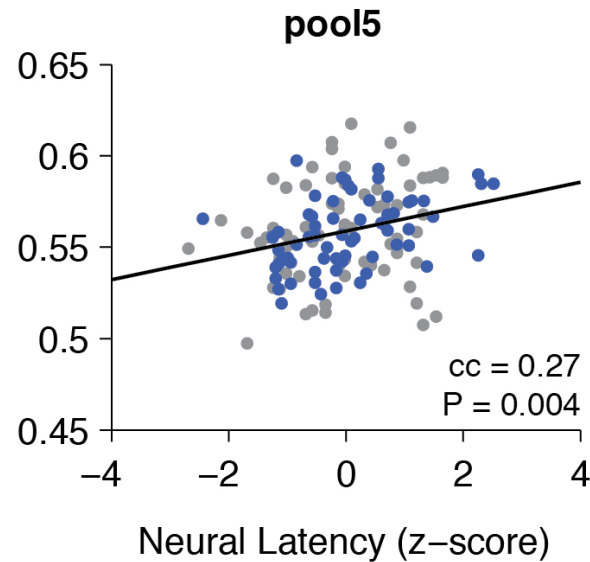


The neural latency for each image was correlated with the distance to category center

A



B



Hopfield network with binary neurons

Each neuron i has two states: $V_i=0$ or $V_i=1$

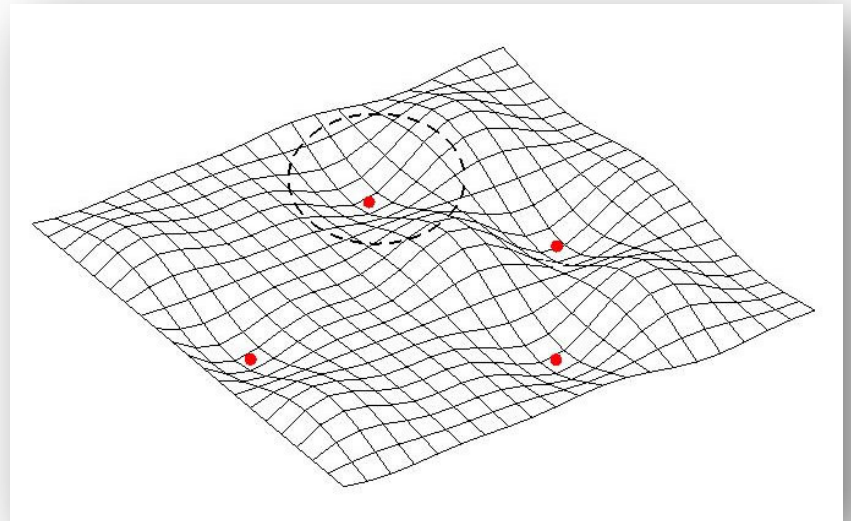
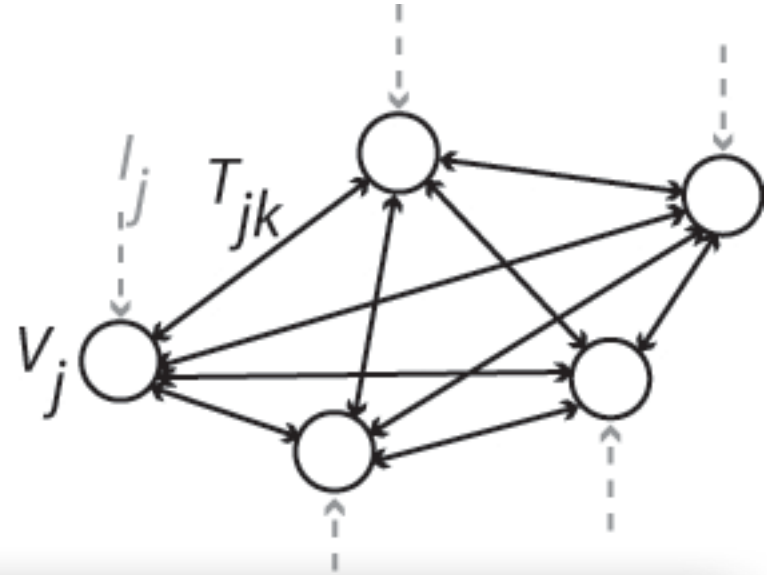
Ensemble: $\mathbf{V} = [V_1, V_2, \dots, V_N]$ Note: $\mathbf{V} = \mathbf{V}(t)$

Synaptic strength: T_{ij}

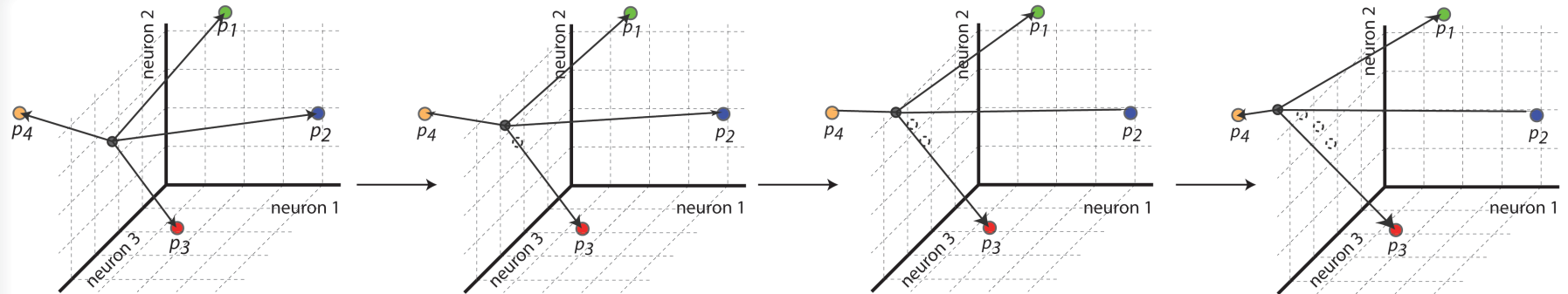
If two neurons are not connected: $T_{ij}=0$

No self connections: $T_{ii}=0$

Update rule: $V_i(t)=1$ iff $\sum_j T_{ij} V_j(t) > 0$

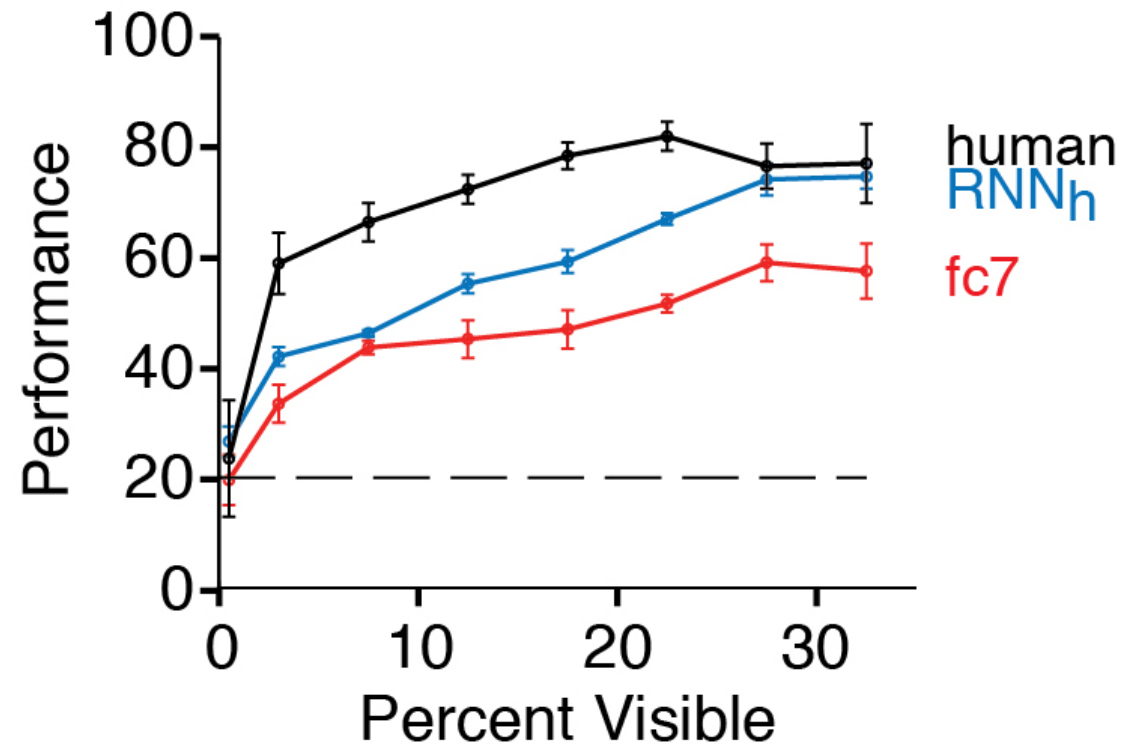
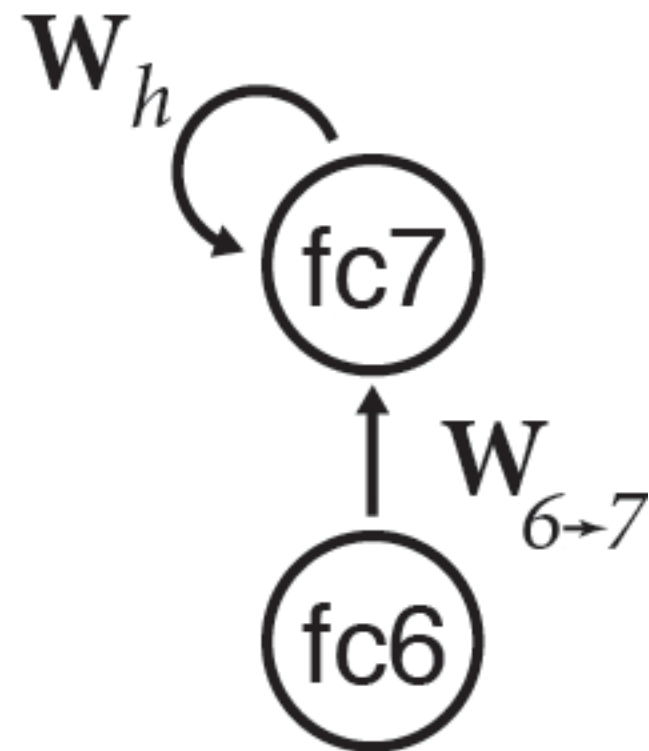


A recurrent network may ameliorate the problem of missing information



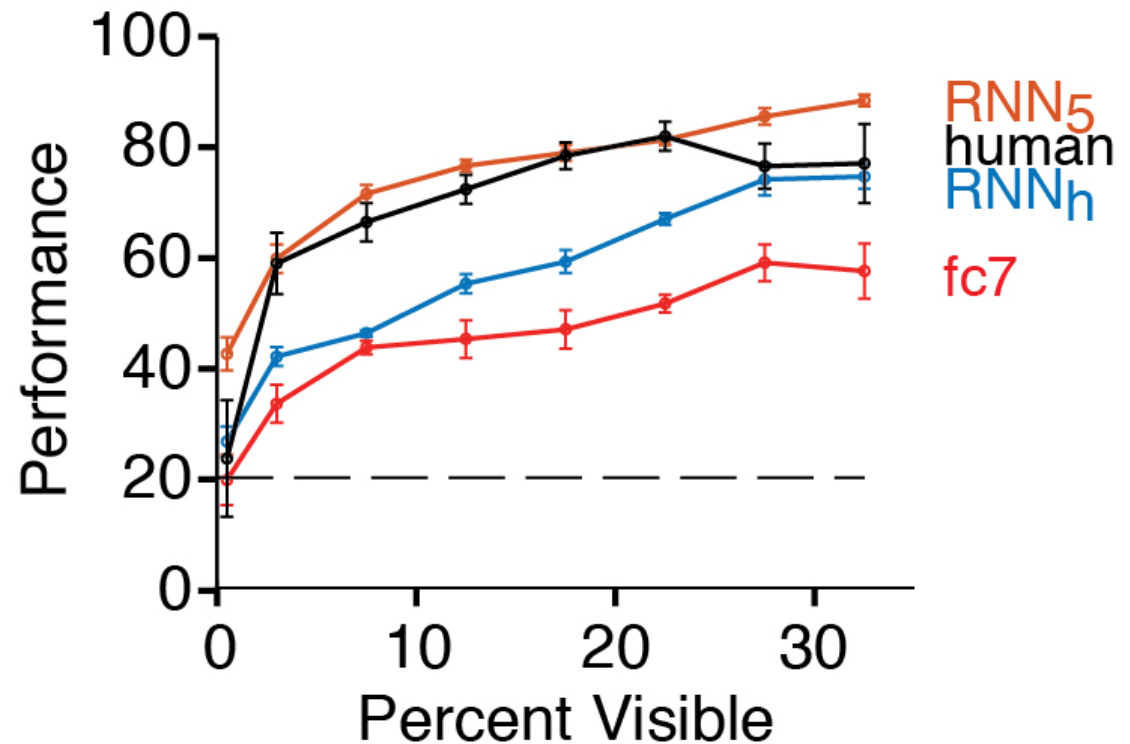
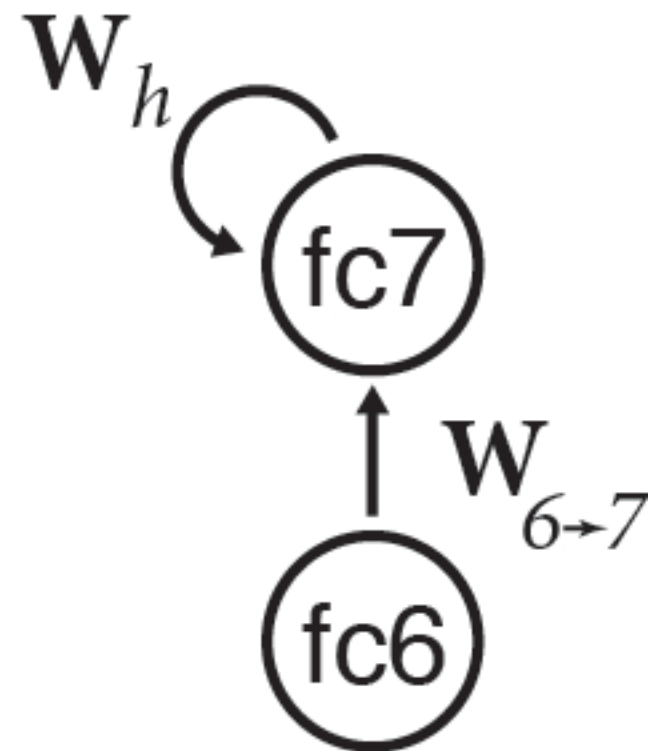
p = prototypes (fixed)

Recurrent Hopfield network (RNN_h) improves recognition performance for partial images



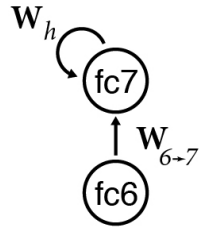
NOTE: 0 free parameters

Training with occluded objects leads to matching human performance in pattern completion

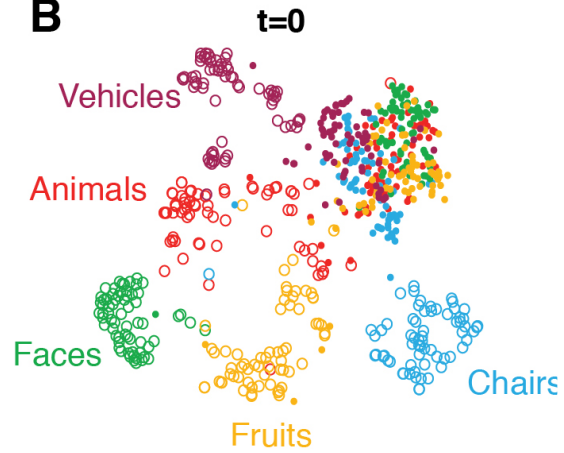


Temporal evolution in recurrent networks

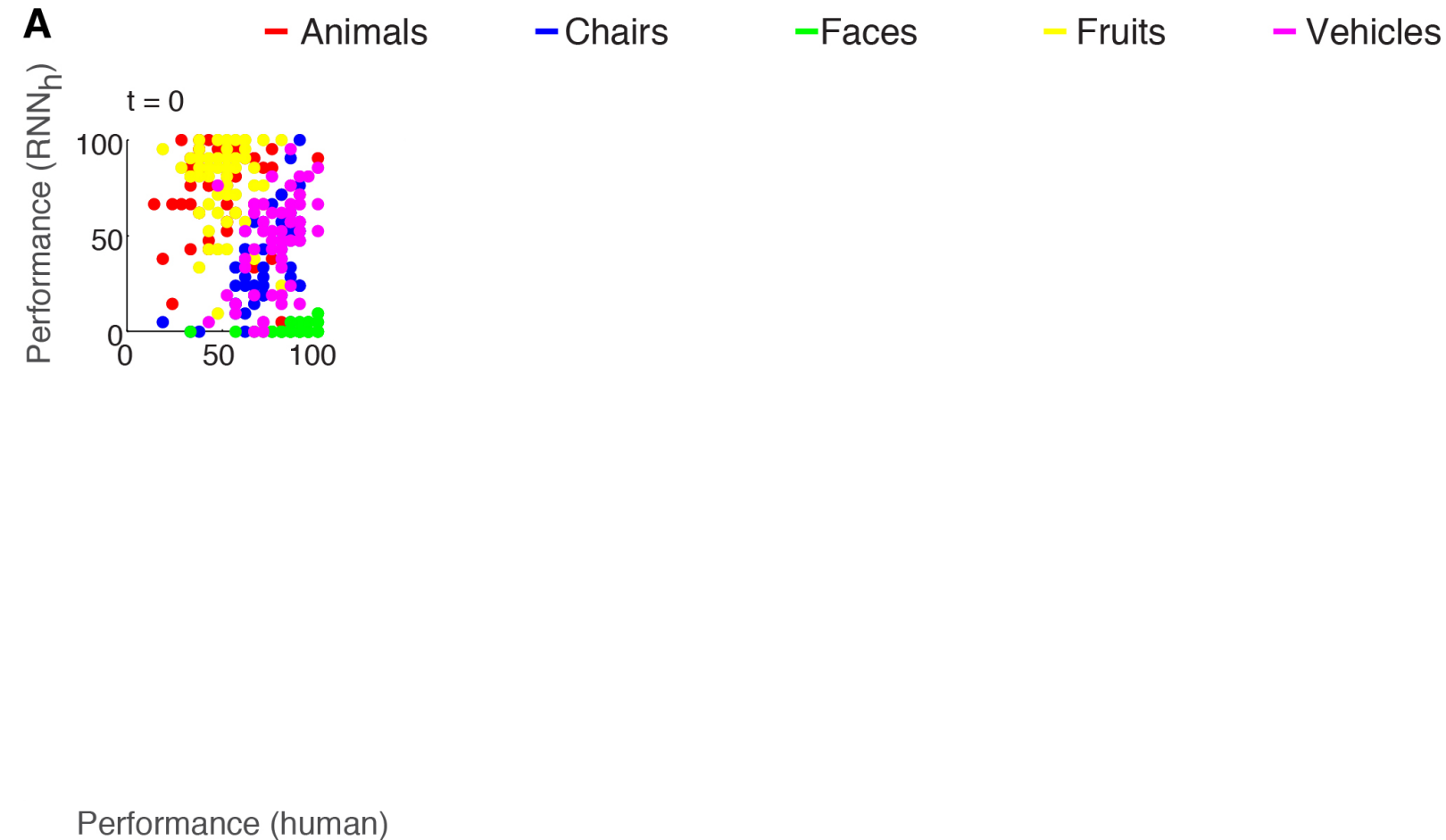
A



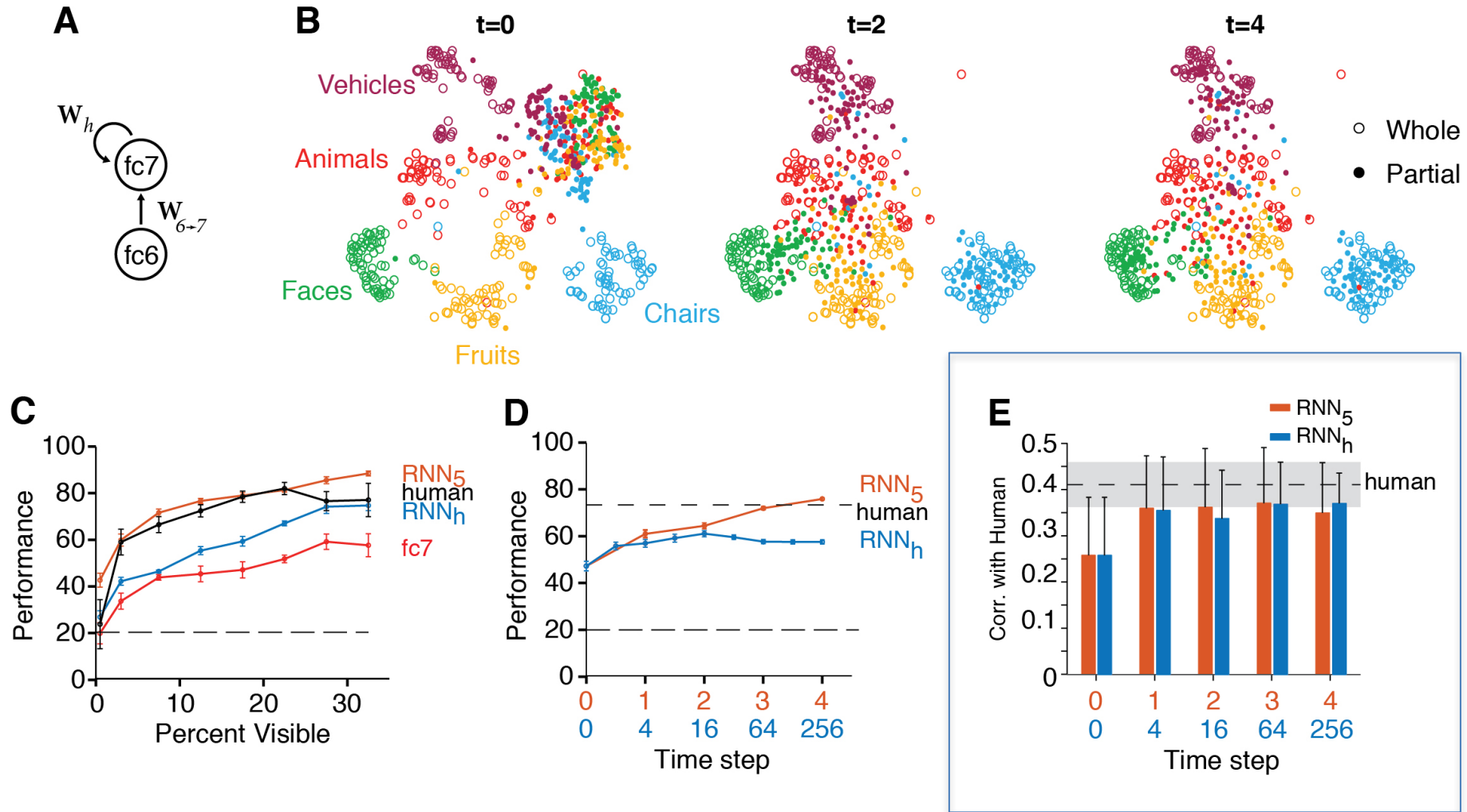
B



Correlation between RNN models and human performance for individual objects



Recurrent neural networks match human performance in pattern completion



Computational roles of recurrent/feedback signals

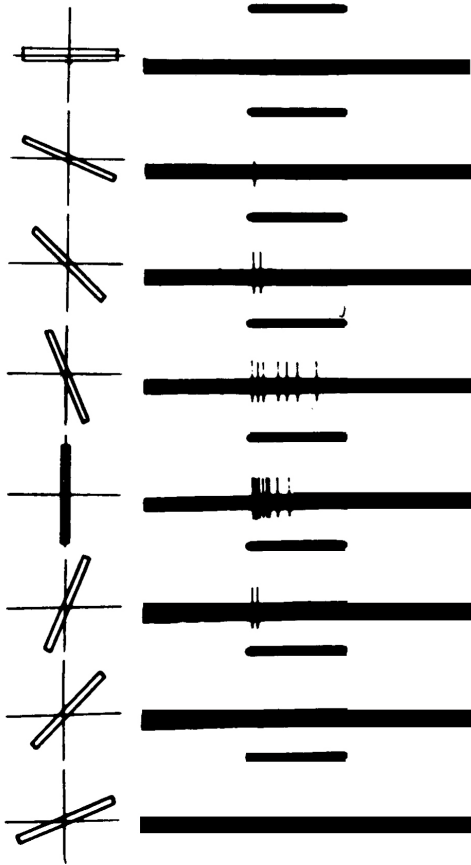
1. Pattern completion (recurrent computations)
2. Predictive coding (feedback computations)



Image by Hanlin Tang

Neurophysiology led the way to basic filters

Orientation selectivity



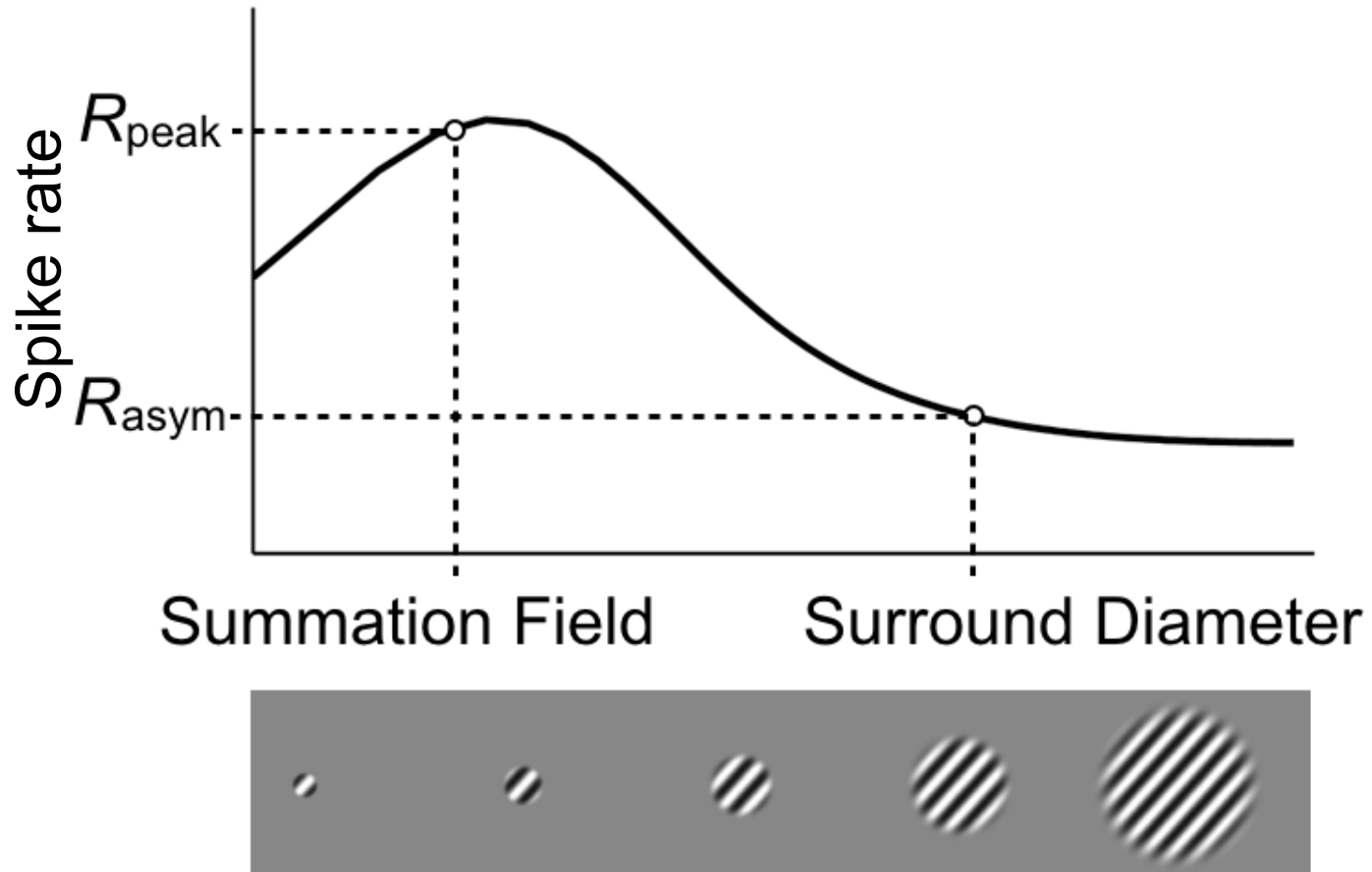
Gabor function

$$D(x,y) = \frac{1}{2\pi\sigma_x\sigma_y} \exp\left[-\frac{x^2}{2\sigma_x^2} - \frac{y^2}{2\sigma_y^2}\right] \cos(kx - \phi)$$

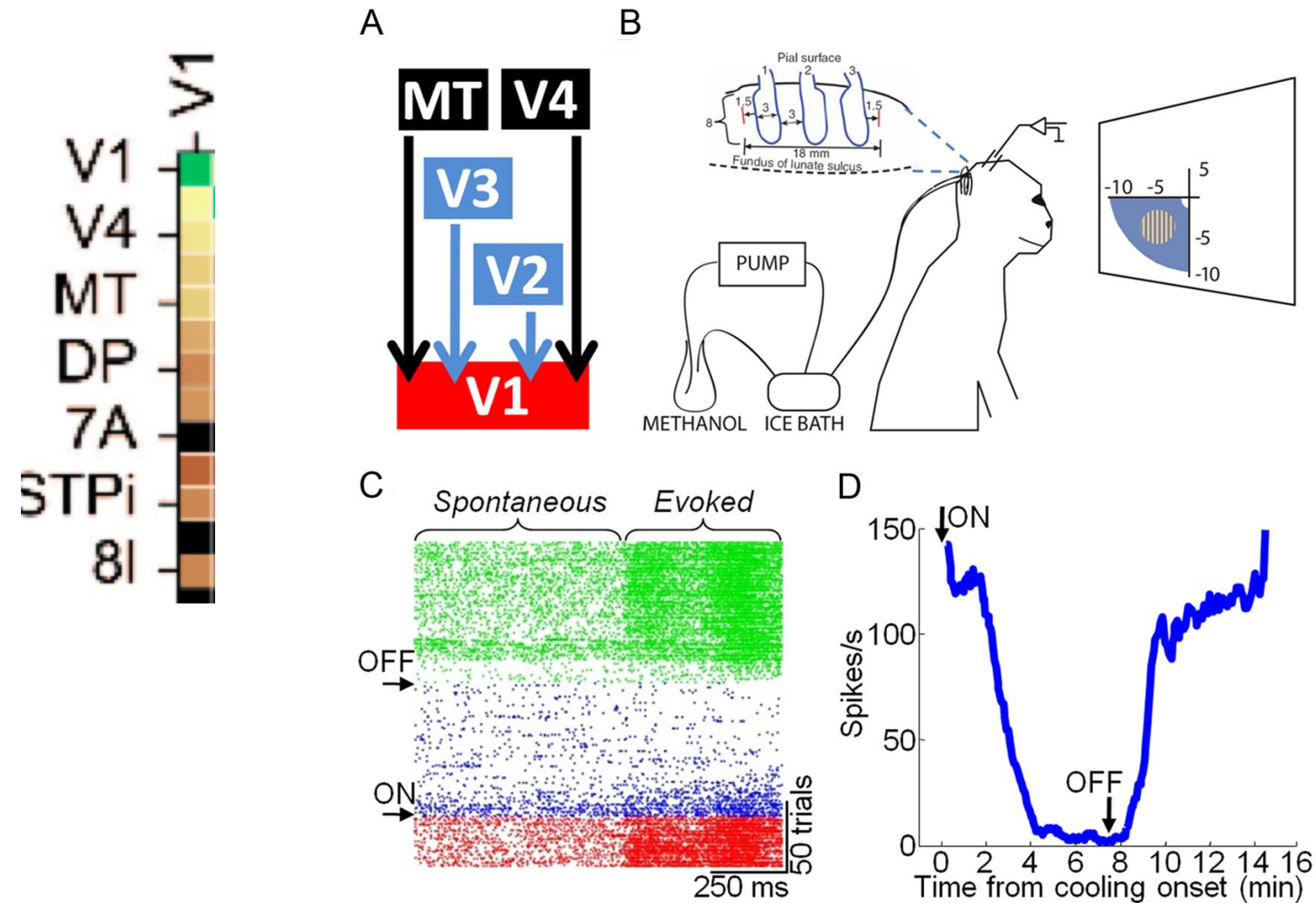
Hubel and Wiesel 1968

Hubel – Nobel Lecture

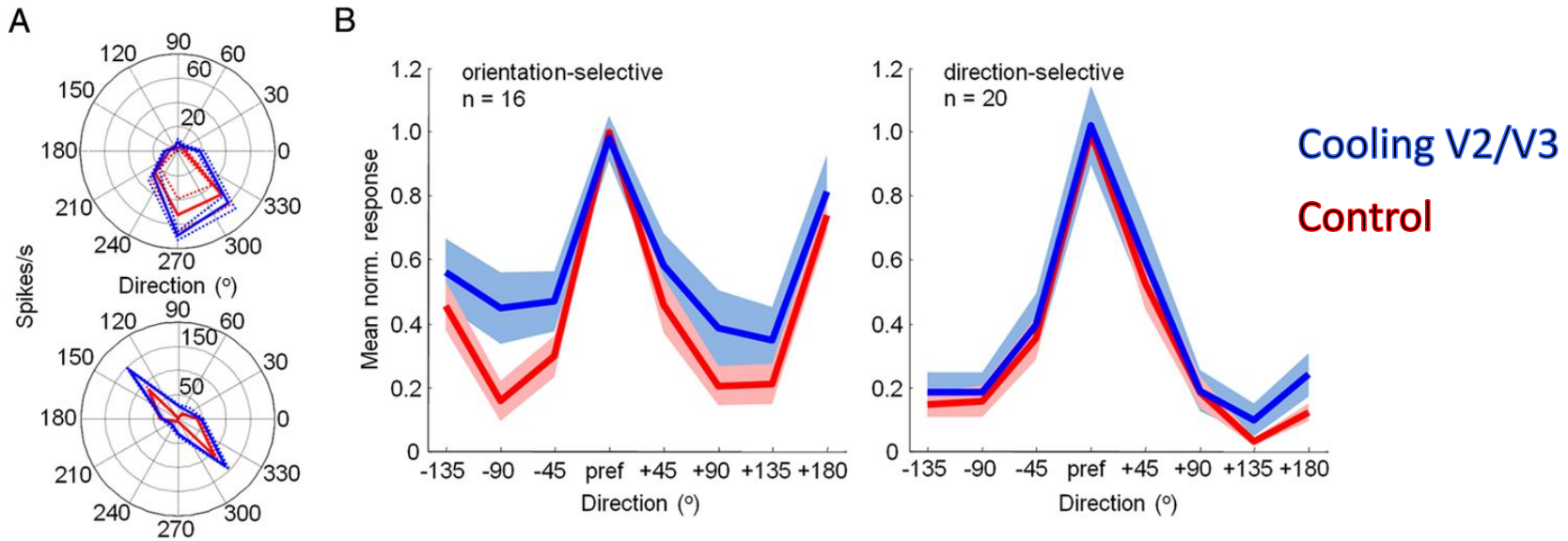
Area summation curve in V1



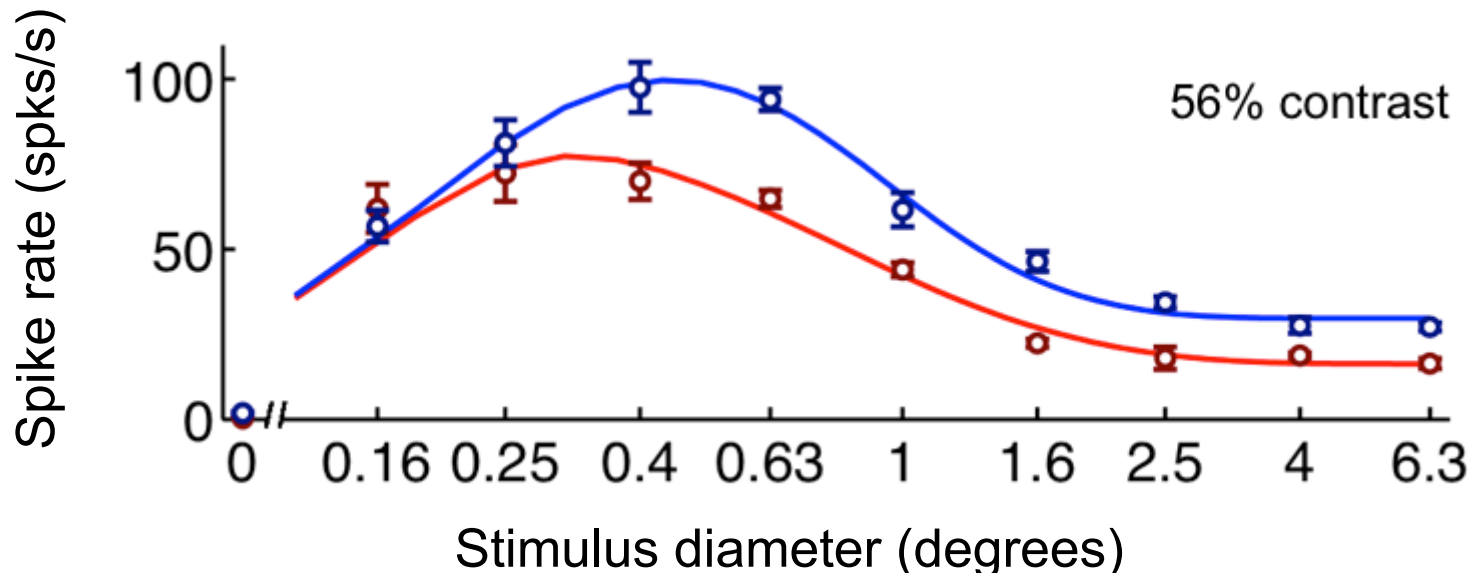
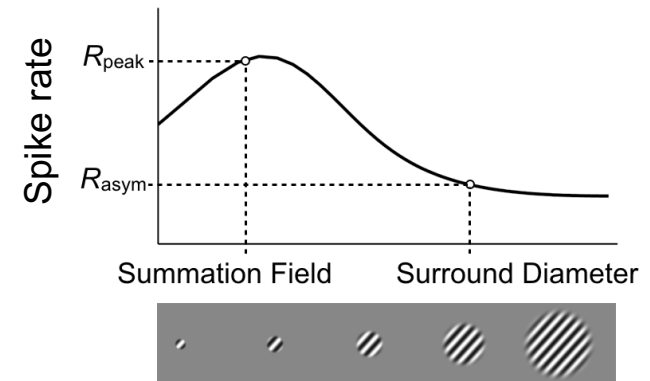
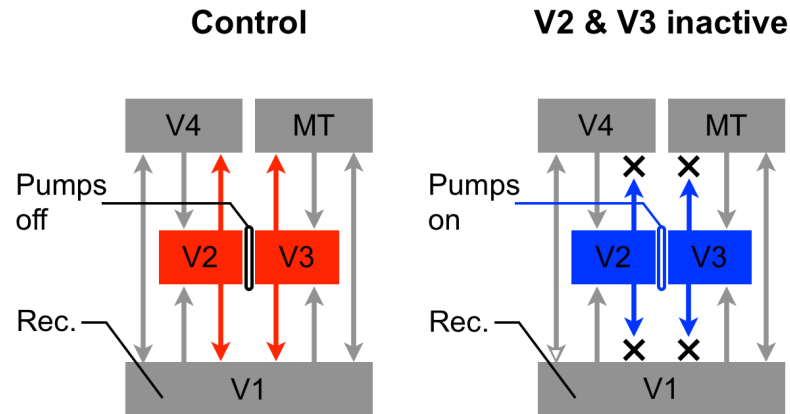
Reversible inactivation of feedback signals (from V2/V3 to V1)



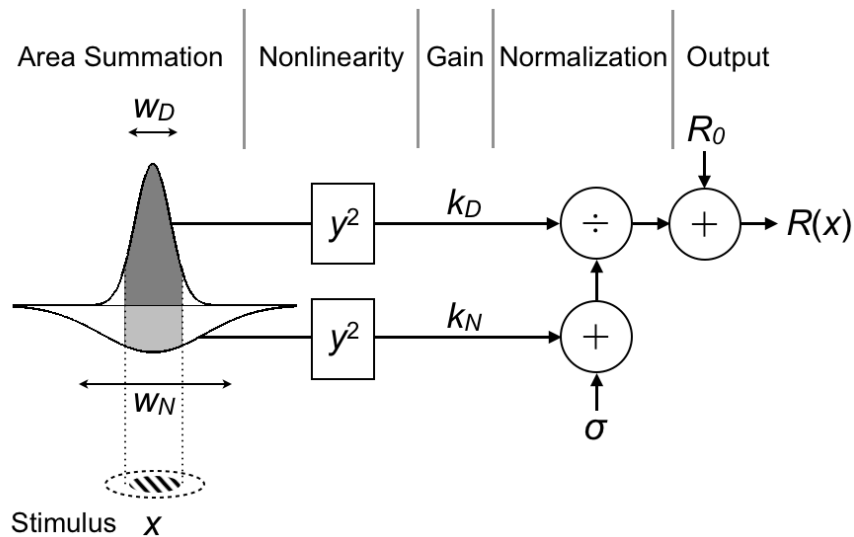
Feedback inactivation does not change orientation or direction selectivity



Feedback inactivation leads to reduced surround suppression

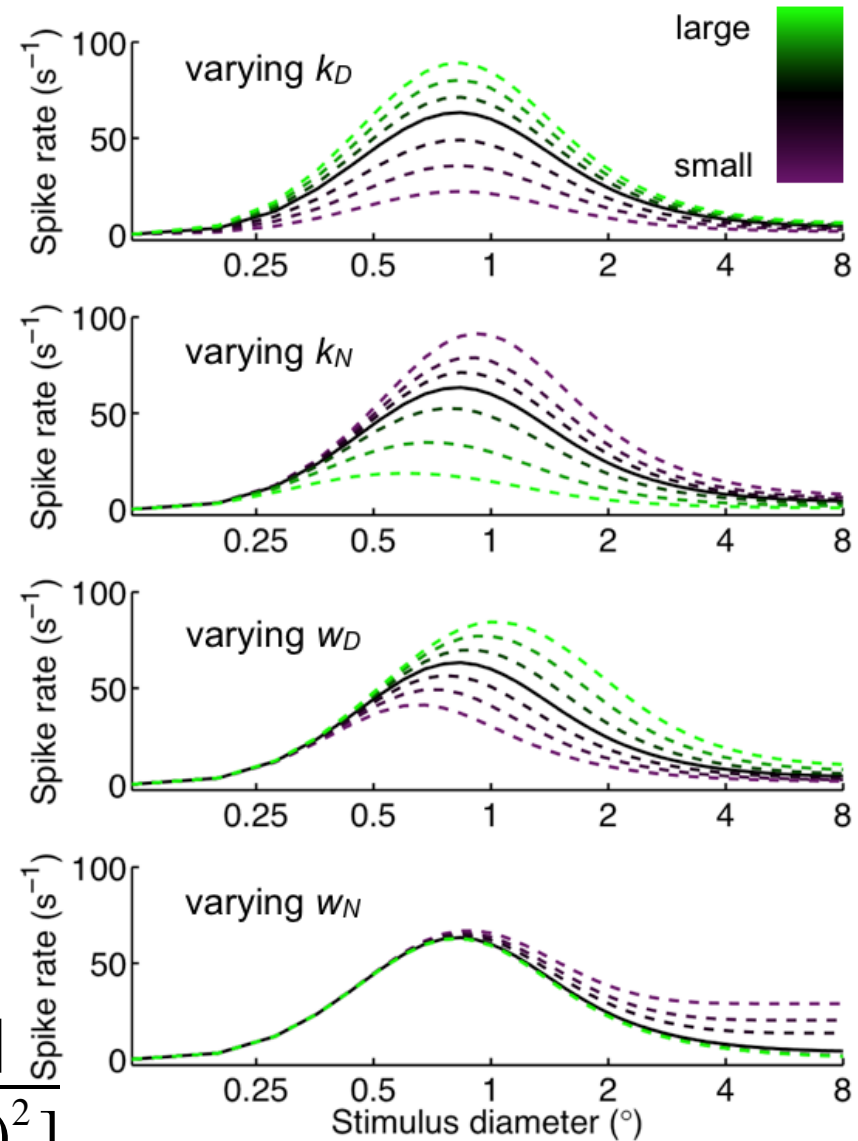


A simple normalization model to explain area summation curves

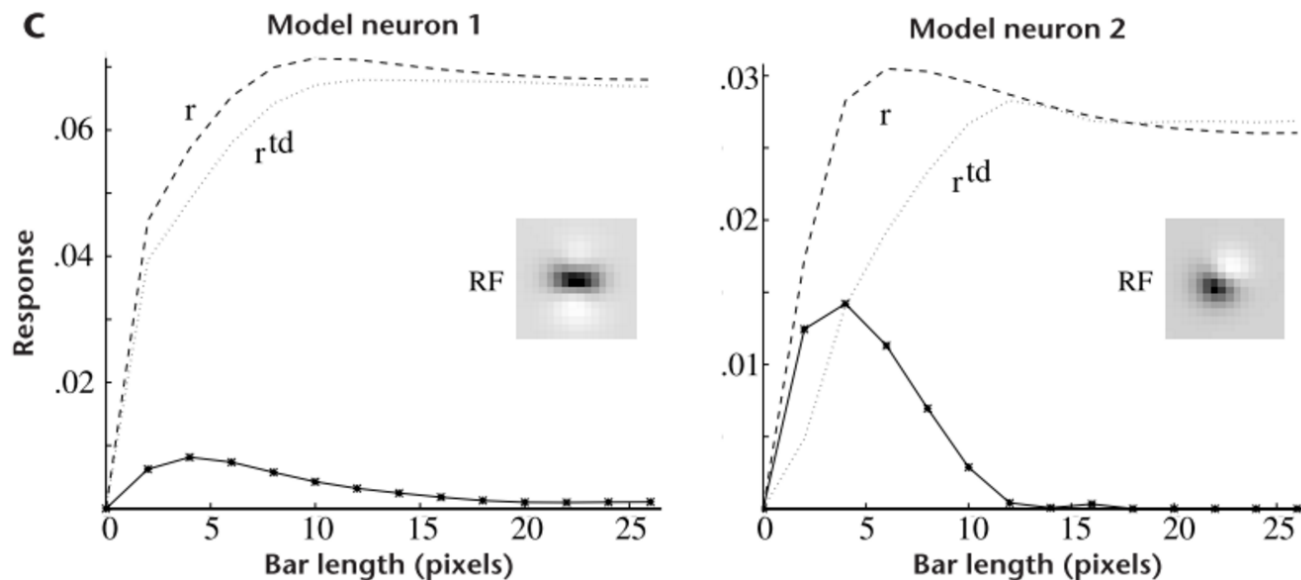
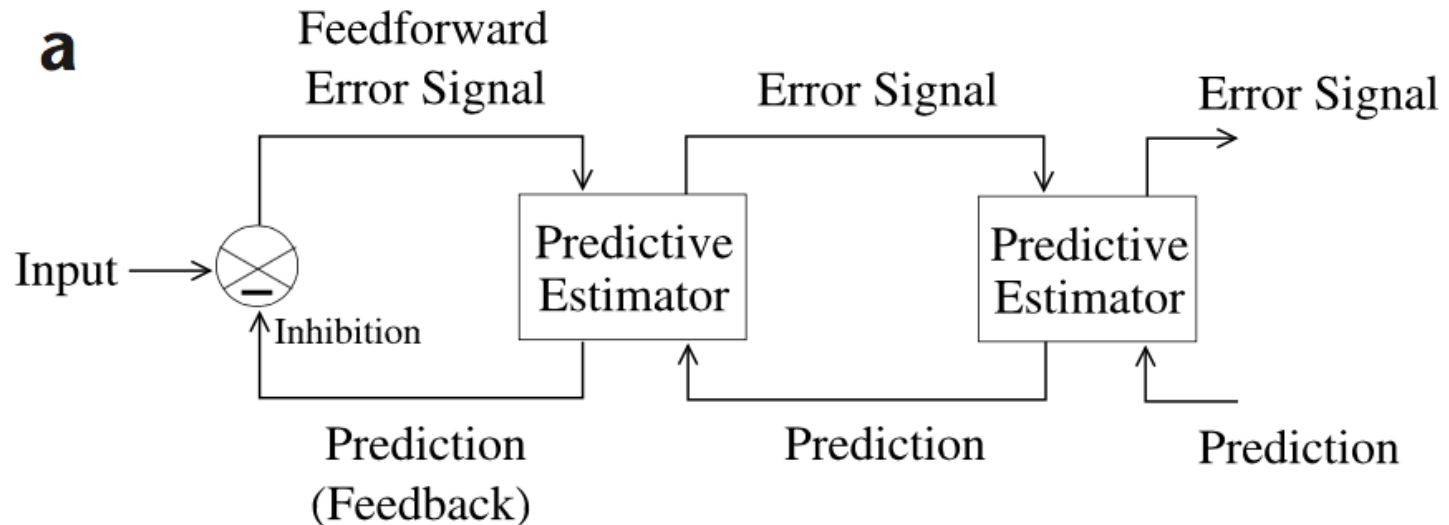


$$R_{ROG}(x) = R_0 + \frac{D(x)}{\sigma + N(x)}$$

$$R_{ROG}(x) = R_0 + \frac{k_D [w_D \operatorname{erf}(x / 2w_D)^2]}{\sigma + k_N [w_N \operatorname{erf}(x / 2w_N)^2]}$$



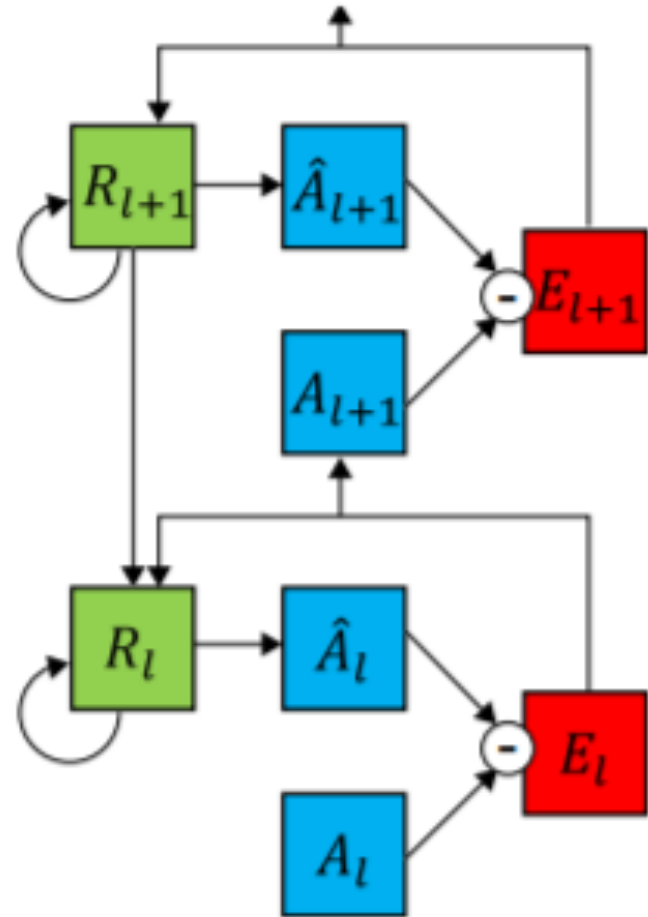
Predictive coding in visual cortex



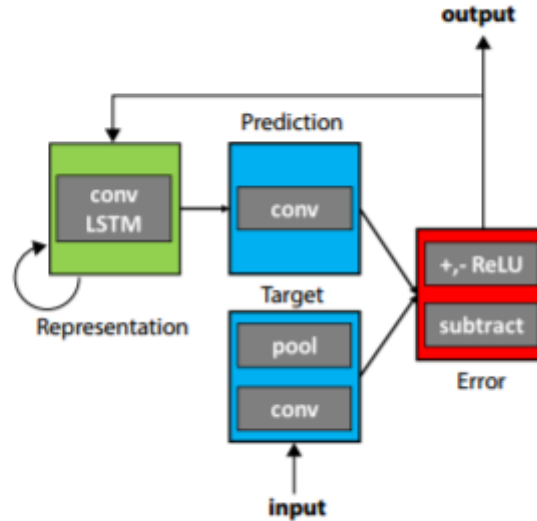
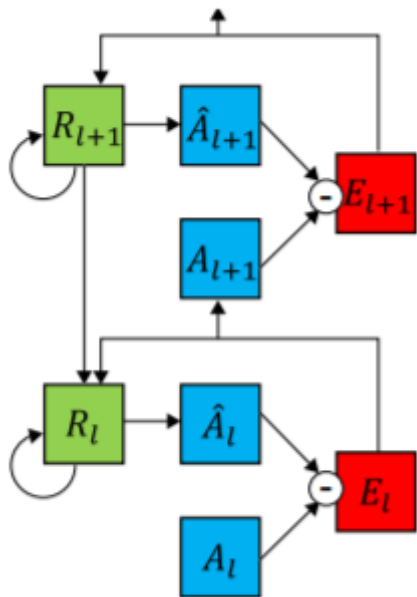
Deep Learning Implementation of Predictive Coding

Essential elements:

- “**Representation**” neurons: hold “state of world”
- **Predictions**
- **Targets**
- “**Error**” neurons



“PredNet” Details



$$A_l^t = \begin{cases} x_t & l=0 \\ \text{MAXPOOL}(\text{RELU}(\text{CONV}(E_{l-1}^t))) & l>0 \end{cases}$$

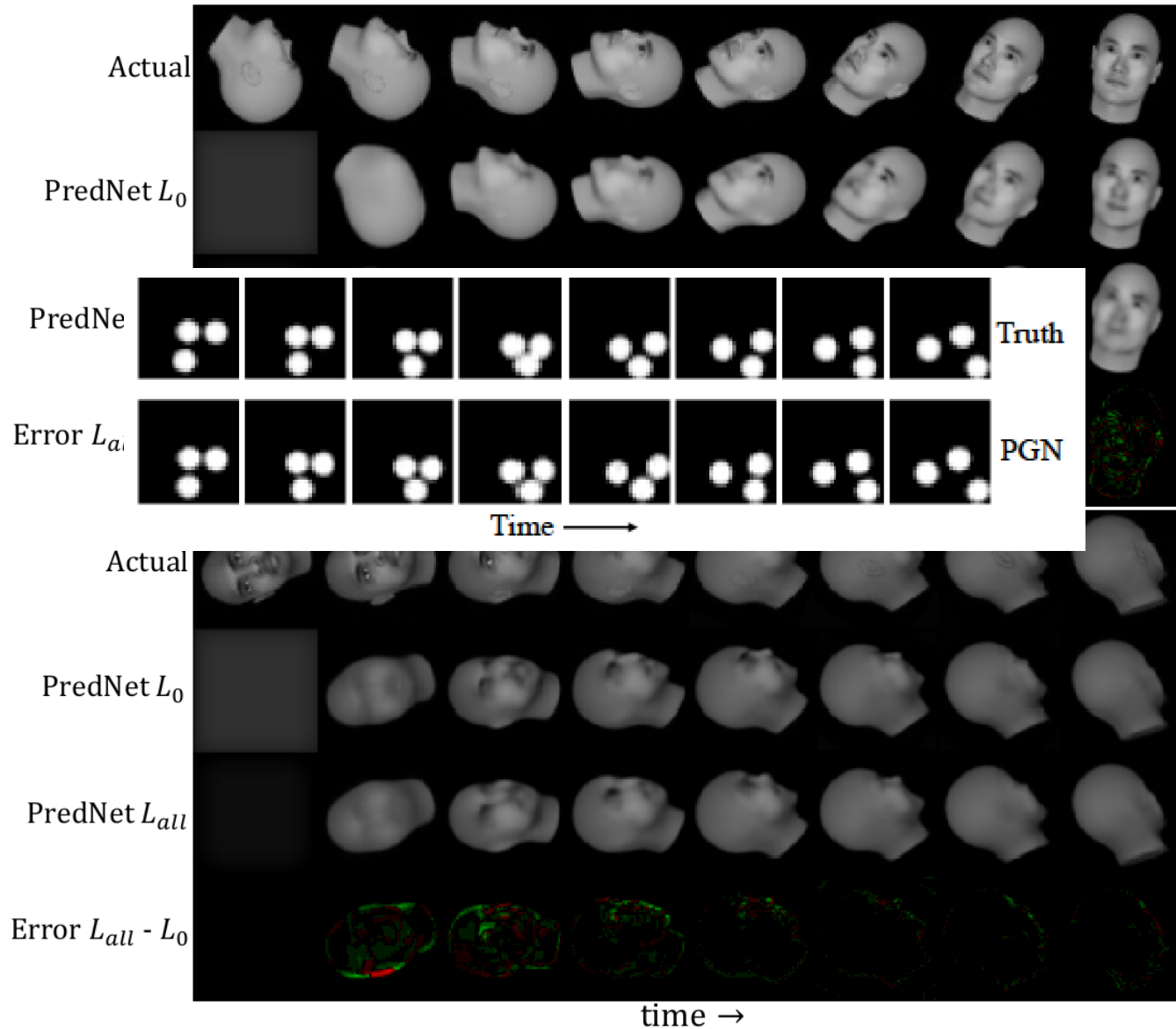
$$\hat{A}_l^t = \text{RELU}(\text{CONV}(R_l^t))$$

$$E_l^t = [\text{RELU}(A_l^t - \hat{A}_l^t); \text{RELU}(\hat{A}_l^t - A_l^t)]$$

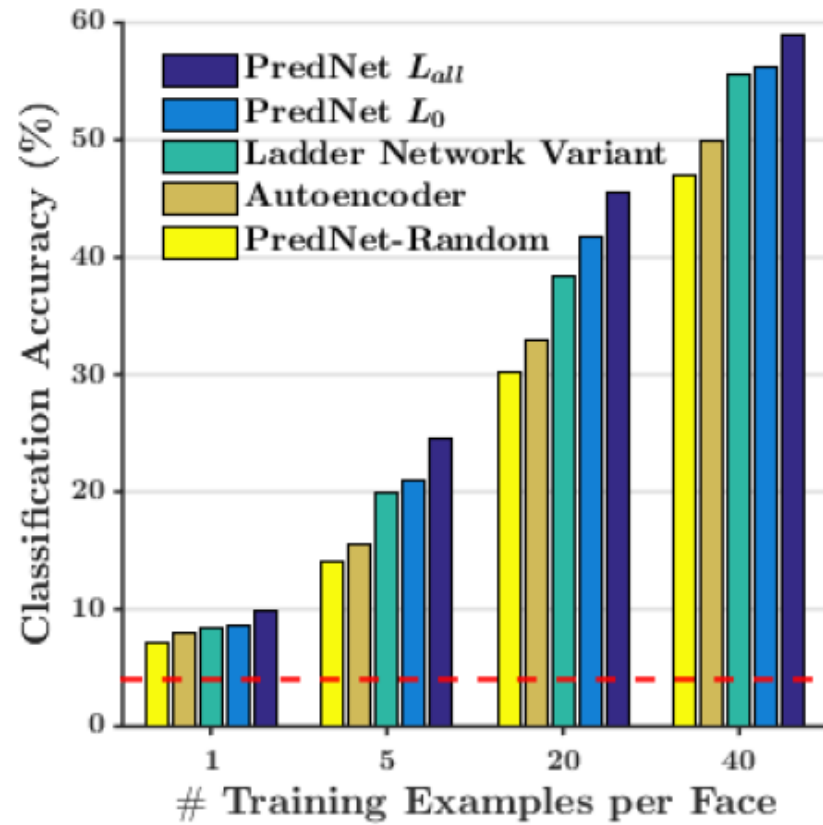
$$R_l^t = \text{CONVLSTM}(E_{l-1}^{t-1}, R_{l-1}^{t-1}, \text{UPSAMPLE}(R_{l+1}^t))$$

$$L = \sum_{t=0}^T \lambda_t \sum_{l=0}^{N_l} \lambda_l / n_l \sum_{i=1}^{n_l} E_l^t(i)$$

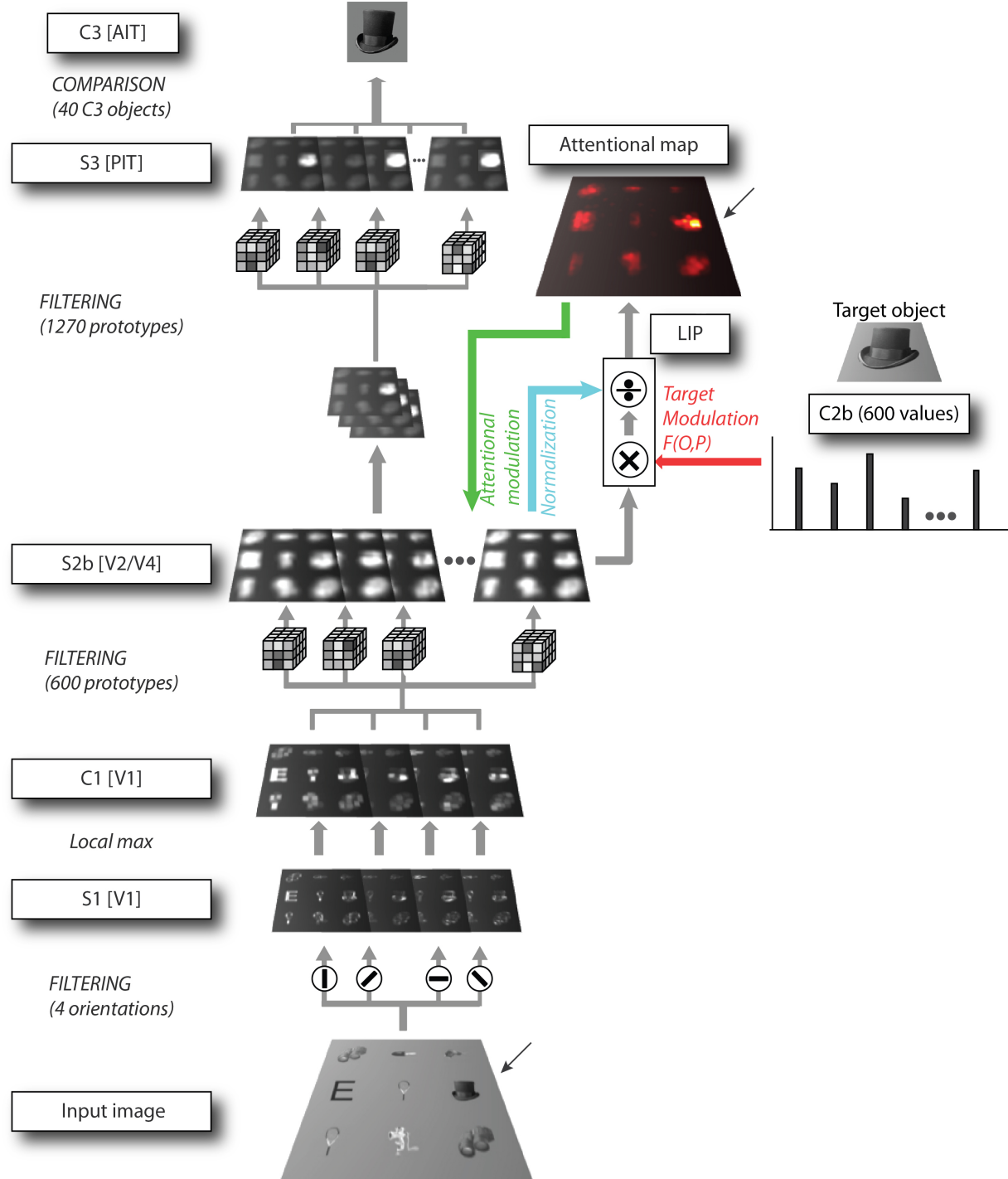
Testing the model with rotating faces



Training for prediction \rightarrow successful image classification



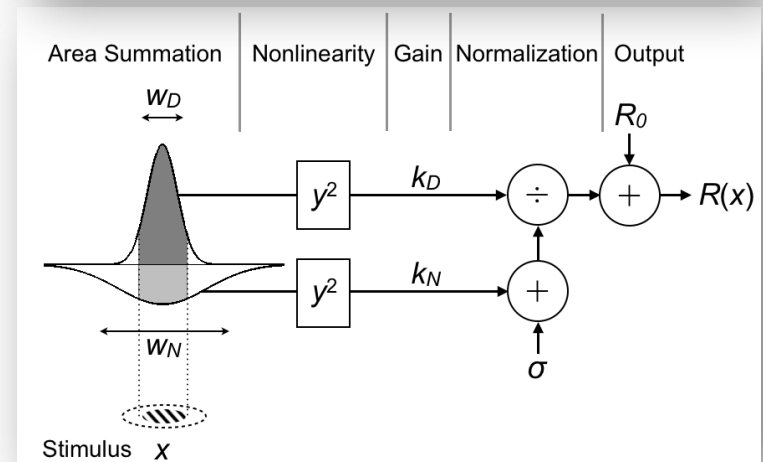
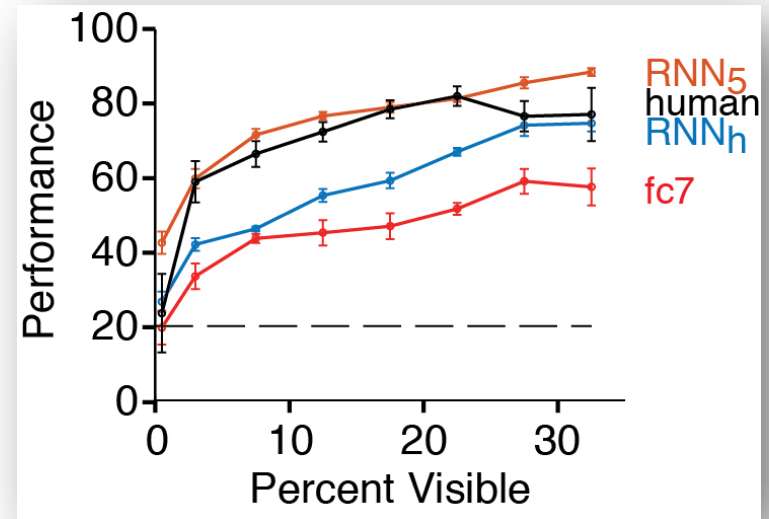
Feedback signals in visual search



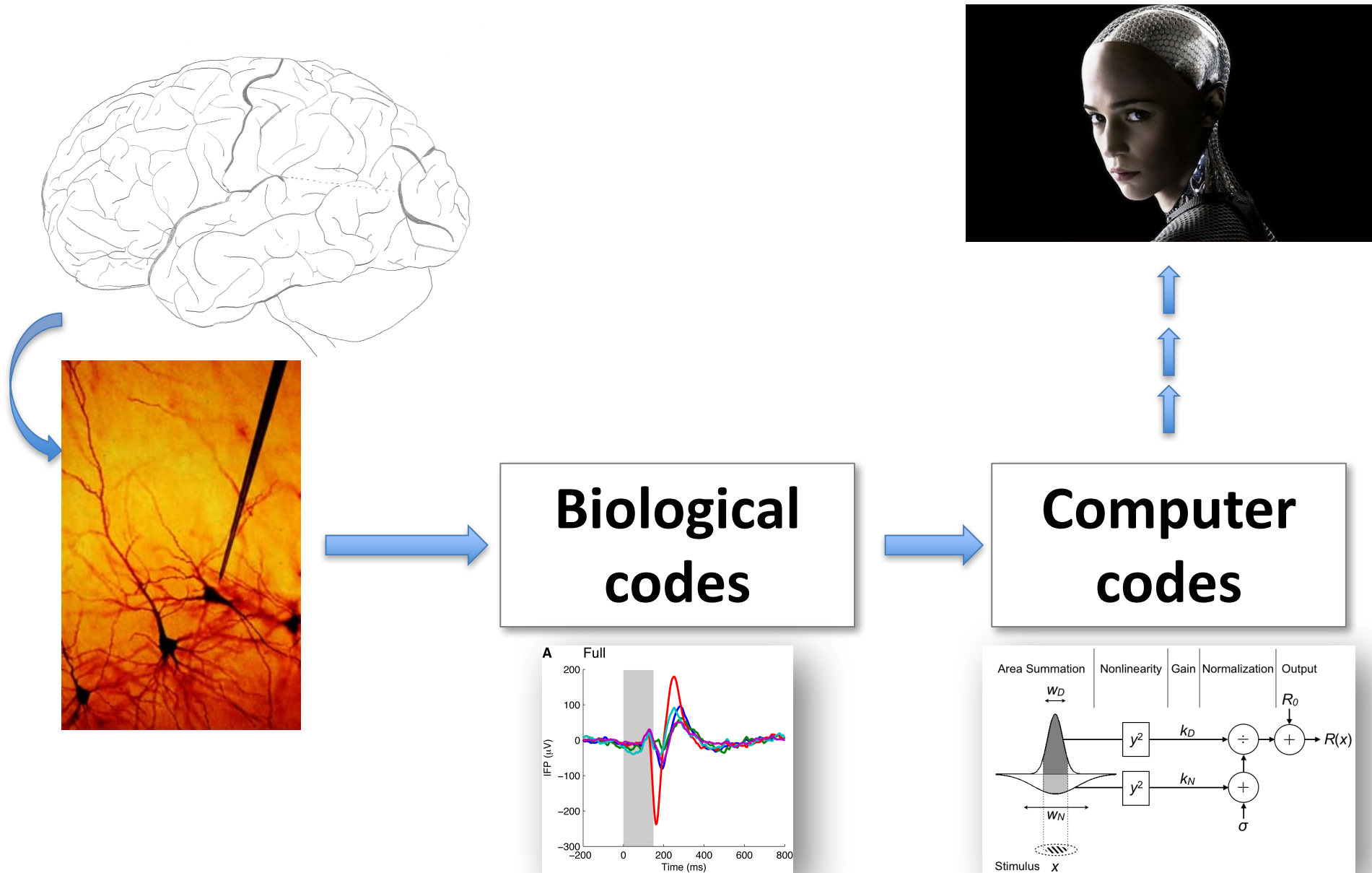
Summary

Pattern completion: Recurrent connections can help recognize heavily occluded objects and pattern completion

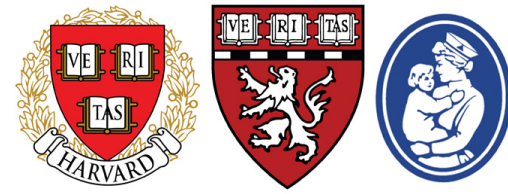
Feedback signals enhance surround suppression and may provide a signal for predictive coding that can help in unsupervised learning



From biological codes to computational codes



Visual recognition: peeking inside computations in the brain



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Center for Brains, Minds and Machines

Camille Gomez



Richard Born



Jojo Nassi



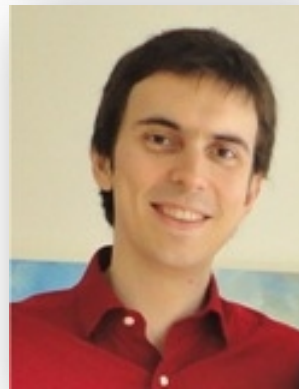
Laura Groomes



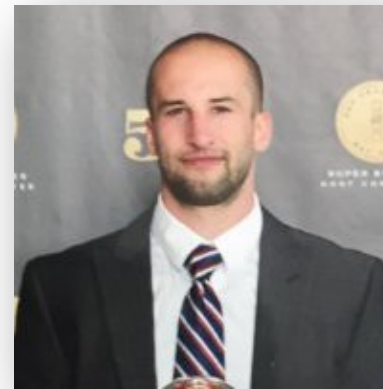
Hanlin Tang



Thomas Miconi



Bill Lotter



David Cox

