Machine Learning: a Basic Toolkit

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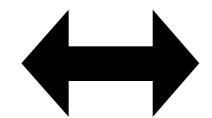
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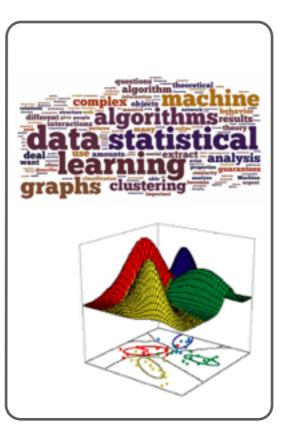
Machine Learning

Intelligent Systems



Data Science









ML Desert Island Compilation

An introduction to essential Machine Learning:

- Concepts
- Algorithms

PART I

Local methods

• Bias-Variance and Cross Validation

PART II

• **Regularization** I: Linear Least Squares

•Regularization II: Kernel Least Squares

Morning

PART III

• Variable Selection: OMP

• Dimensionality Reduction: PCA

PART IV

Matlab practical session

Afternoon

PART I

- Local methods
- Bias-Variance and Cross Validation

GOAL: Investigate the trade-off between stability and fitting starting from simple machine learning approaches

The goal of supervised learning is to find an underlying input-output relation $f(x_{new}) \sim y$,

given data.

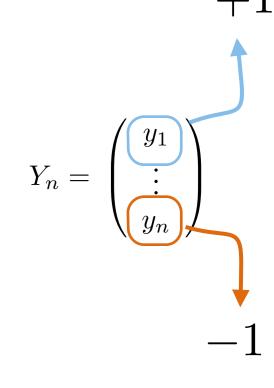
The data, called *training set*, is a set of n input-output pairs,

$$S = \{(x_1, y_1), \dots, (x_n, y_n)\}.$$

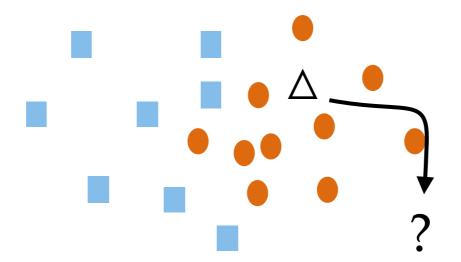


.	170	238	85	255	221	0
	68	136	17	170	119	68
	221	0	238	136	0	255
	119	255	85	170	136	238
	238	17	221	68	119	255
	85	170	119	221	17	136

$$X_n = \begin{pmatrix} x_1^1 & \dots & \dots & x_1^p \\ \vdots & \vdots & \vdots & \vdots \\ x_n^1 & \dots & \dots & x_n^p \end{pmatrix}$$







Local Methods: Nearby points have similar labels

Nearest Neighbor

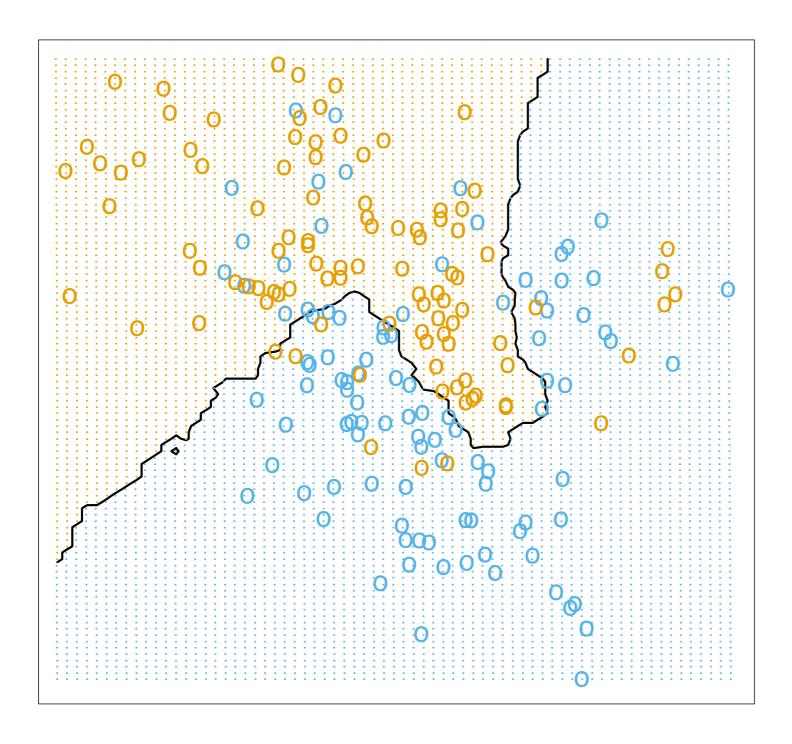
Given an input \bar{x} , let

$$i' = \arg\min_{i=1,...,n} \|\bar{x} - x_i\|^2$$

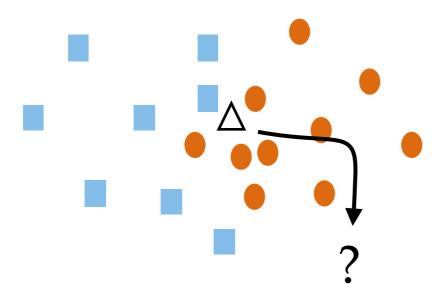
and define the nearest neighbor (NN) estimator as

$$\hat{f}(\bar{x}) = y_{i'}.$$

How does it work?



Plot



K-Nearest Neighbors

Consider

$$d_{\bar{x}} = (\|\bar{x} - x_i\|^2)_{i=1}^n$$

the array of distances of a new point \bar{x} to the input points in the training set. Let

 $s_{\bar{x}}$

be the above array sorted in increasing order and

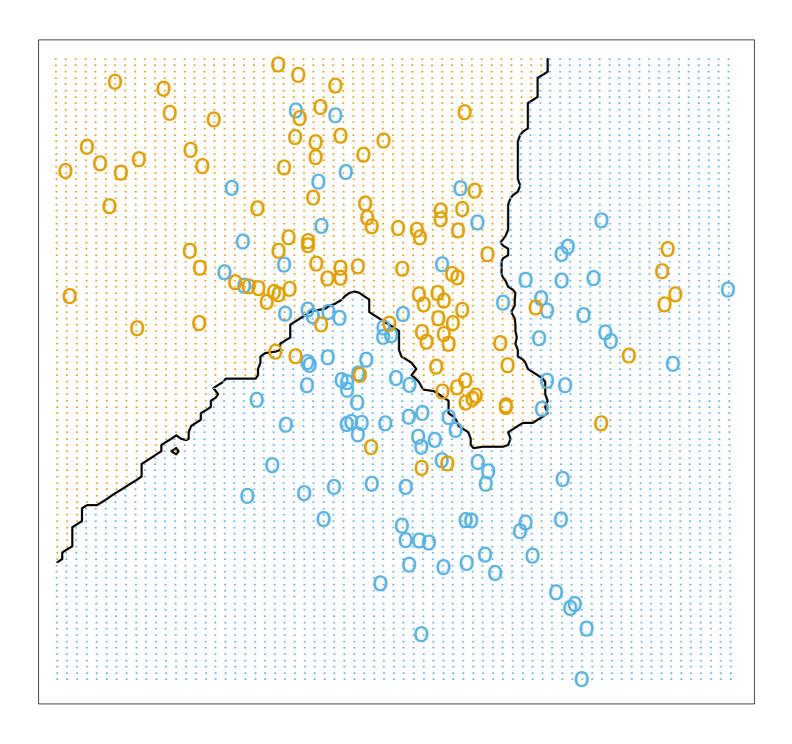
 $I_{\bar{x}}$

the corresponding vector of indices, and

$$K_{\bar{x}} = \{I_{\bar{x}}^1, \dots, I_{\bar{x}}^K\}$$

be the array of the first K entries of $I_{\bar{x}}$. The K-nearest neighbor estimator (KNN) is defined as,

$$\hat{f}(\bar{x}) = \sum_{i' \in K_{\bar{x}}} y_{i'},$$



Plot

Remarks:

Generalization I: closer points should count more

$$\hat{f}(\bar{x}) = \frac{\sum_{i=1}^{n} y_i k(\bar{x}, x_i)}{\sum_{i=1}^{n} k(\bar{x}, x_i)},$$
 Gaussian $k(x', x) = e^{-\|x - x'\|^2 / 2\sigma^2}.$

Parzen Windows

Generalization II: other metric/similarities

$$X = \{0, 1\}^D$$

$$d_H(x, \bar{x}) = \frac{1}{D} \sum_{j=1}^D \mathbf{1}_{[x^j \neq \bar{x}^j]}$$

There is one parameter controlling fit/stability

How do we choose it?

Is there an optimal value?

Can we compute it?

Is there an optimal value?

Ideally we would like to choose K that minimizes the expected error

$$\mathbf{E}_S \mathbf{E}_{x,y} (y - \hat{f}_K(x))^2.$$

Next: Characterize corresponding minimization problem to uncover one of **the most fundamental aspect of machine learning**.

For the sake of simplicity we consider a regression model

$$y_i = f_*(x_i) + \delta_i$$
, $\mathbf{E}\delta_I = 0$, $\mathbf{E}\delta_i^2 = \sigma^2$ $i = 1, \dots, n$

$$\mathbf{E}_{S}\mathbf{E}_{x,y}(y-\hat{f}_{K}(x))^{2} = \mathbf{E}_{x}\underbrace{\mathbf{E}_{S}\mathbf{E}_{y|x}(y-\hat{f}_{K}(x))^{2}}_{\varepsilon(K)}.$$

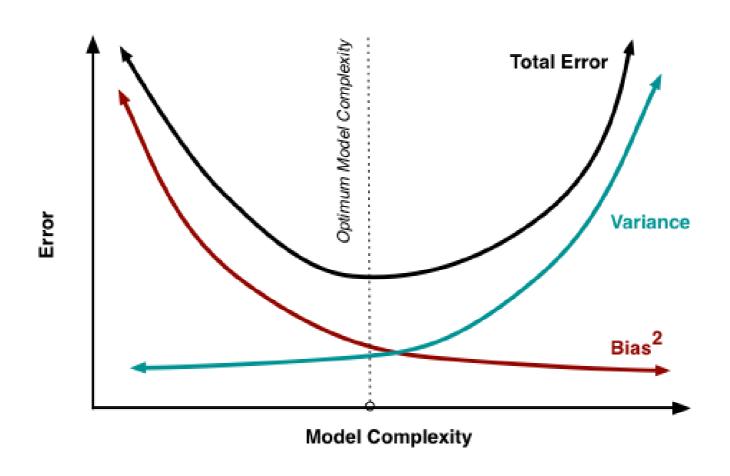
$$\mathbf{E}_{y|x}\hat{f}_K(x) = \frac{1}{K} \sum_{\ell \in K_x} f_*(x_\ell).$$

$$\mathbf{E}_{S}\mathbf{E}_{y|x}(f_{*}(x) - \hat{f}_{K}(x))^{2} = \underbrace{(f_{*}(x) - \mathbf{E}_{S}\mathbf{E}_{y|x}\hat{f}_{K}(x))^{2}}_{Bias} + \underbrace{\mathbf{E}_{S}\mathbf{E}_{y|x}(\mathbf{E}_{y|x}\hat{f}_{K}(x) - \hat{f}_{K}(x))^{2}}_{Variance}$$

$$(f_{*}(x) + \frac{1}{K}\sum_{\ell \in K_{x}} f_{*}(x_{\ell}))^{2}$$

Bias Variance Trade-Off

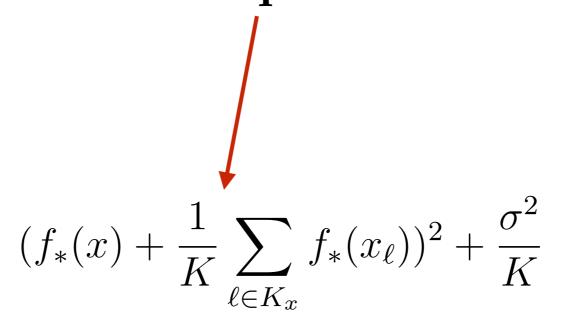
$$(f_*(x) + \frac{1}{K} \sum_{\ell \in K_x} f_*(x_\ell))^2 + \frac{\sigma^2}{K}$$



Is there an optimal value? YES!

Can we compute it?

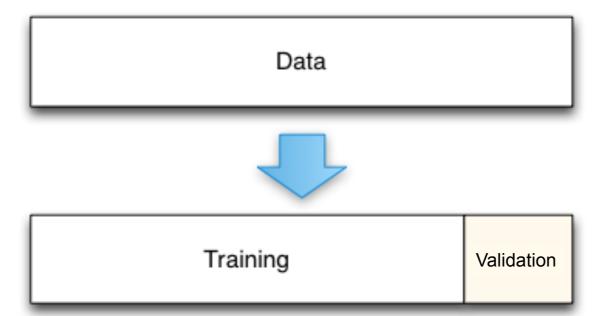
Not quite...



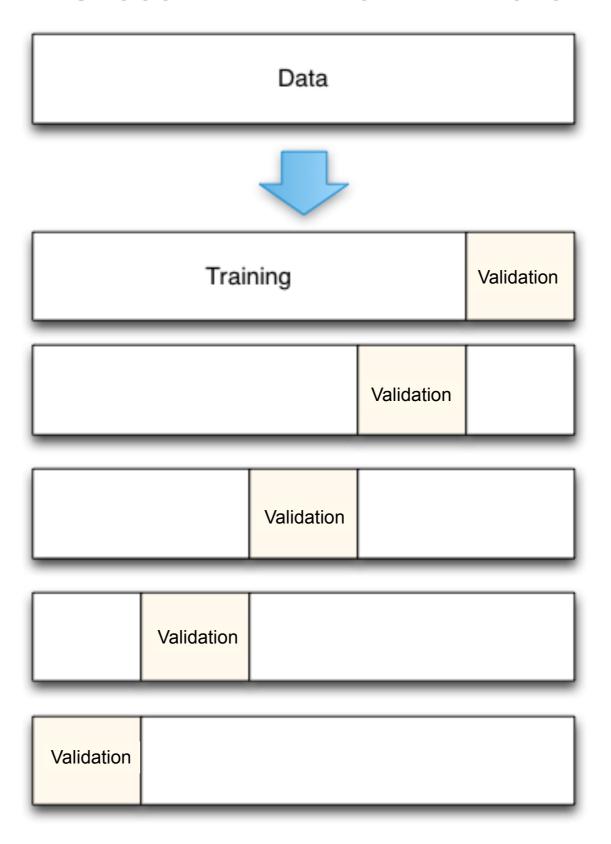
...enter Cross Validation

Split data: train on some, tune on some other

Cross Validation Flavors



Cross Validation Flavors



V-Fold, (V=n is Leave-One-Out)

End of PART I

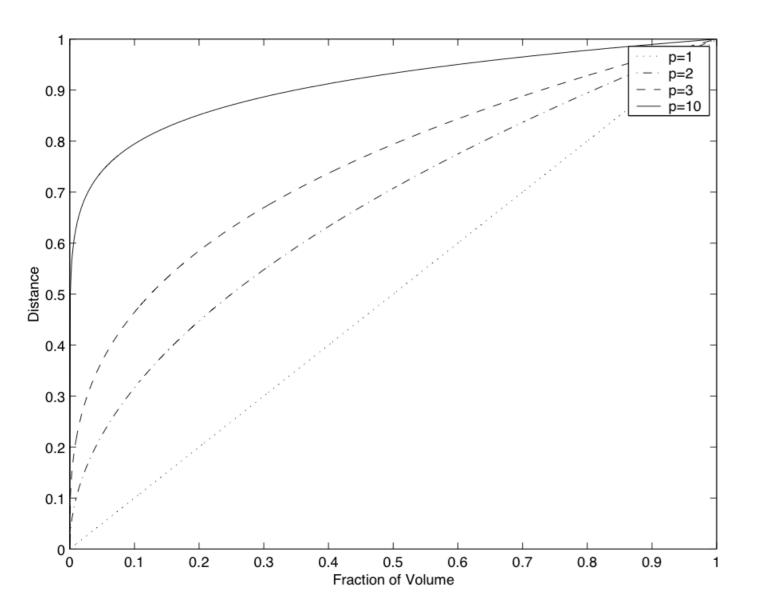
- Local methods
- Bias-Variance and Cross Validation

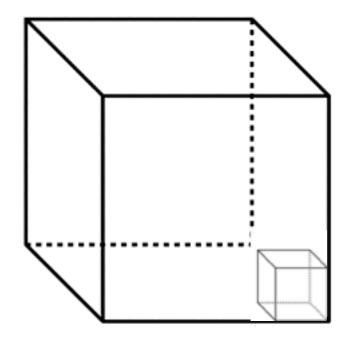
Stability - Overfitting - Bias/Variance - Cross-Validation

End of the Story?

High Dimensions and Neighborhood

tell me the length of the edge of a cube containing 1% of the volume of a cube with edge 1





Cubes and Dth-roots

Curse of dimensionality!

PART II

- Regularization I: Linear Least Squares
- Regularization II: Kernel Least Squares

GOAL: Introduce the basic (global) regularization methods with parametric and non parametric models

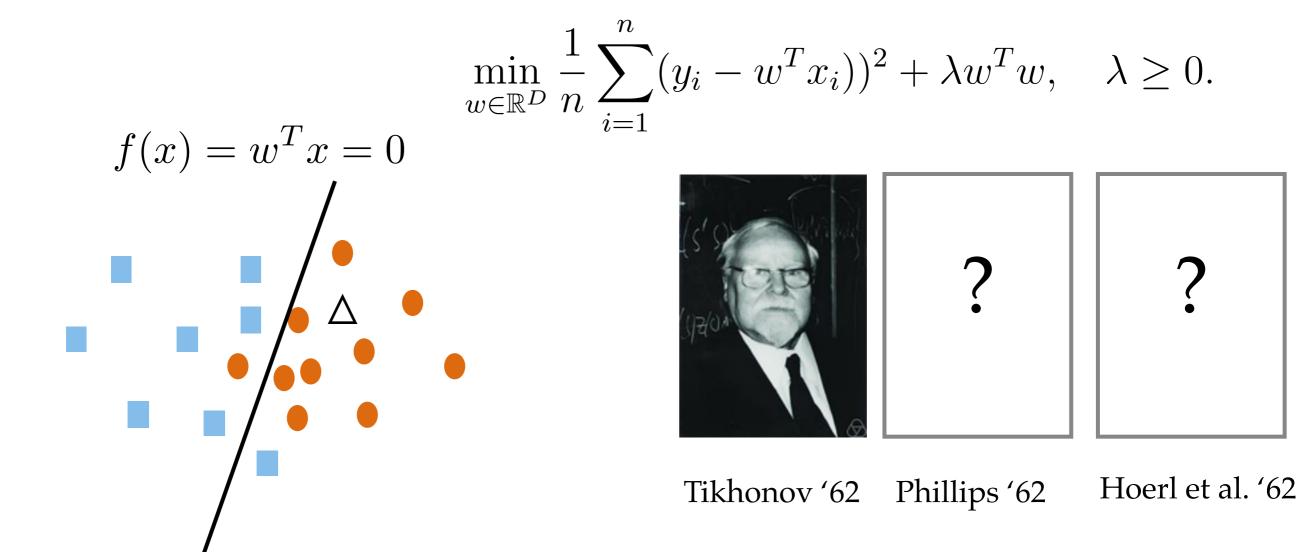
Going Global + Impose Smoothness

Of all the principles which can be proposed for that purpose, I think there is none more general, more exact, and more easy of application, that of which we made use in the preceding researches, and which consists of rendering the sum of squares of the errors a minimum.

(Legendre 1805)



We consider the following algorithm

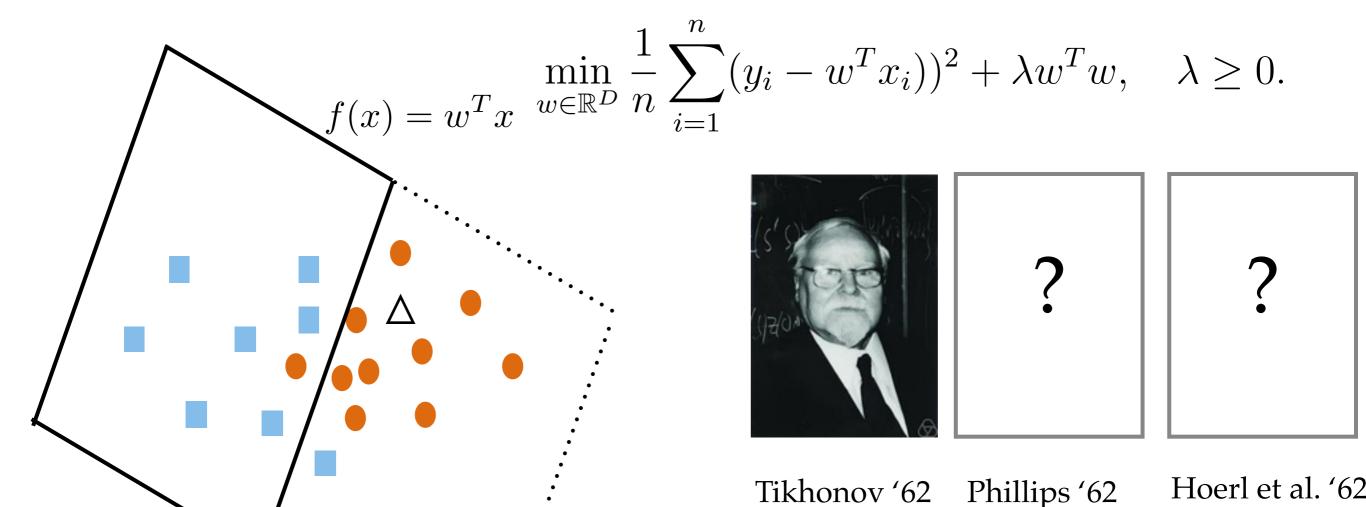


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(Legendre 1805)



We consider the following algorithm



$$\min_{w \in \mathbb{R}^D} \frac{1}{n} \sum_{i=1}^n (y_i - w^T x_i)^2 + \lambda w^T w, \quad \lambda \ge 0.$$

Computations?

Statistics?

$$\min_{w \in \mathbb{R}^D} \frac{1}{n} \sum_{i=1}^n (y_i - w^T x_i)^2 + \lambda w^T w, \quad \lambda \ge 0.$$

Computations?

Notation
$$\frac{1}{n} \sum_{i=1}^{n} (y_i - w^T x_i)^2 = \frac{1}{n} ||Y_n - X_n w||^2$$

$$-\frac{2}{n}X_n^T(Y_n-X_nw)$$
, and, $2w$ Setting gradients...

...to zero

$$(X_n^T X_n + \lambda nI)w = X_n^T Y_n$$

OK, but what is this doing?

Interlude: Linear Systems

$$Ma = b,$$

• If M is a diagonal $M = diag(\sigma_1, \dots, \sigma_D)$ where $\sigma_i \in (0, \infty)$ for all $i = 1, \dots, D$, then $M^{-1} = diag(1/\sigma_1, \dots, 1/\sigma_D), \quad (M + \lambda I)^{-1} = diag(1/(\sigma_1 + \lambda), \dots, 1/(\sigma_D + \lambda))$

• If M is symmetric and positive definite, then considering the eigendecomposition

$$M^{-1} = V \Sigma V^T$$
, $\Sigma = diag(\sigma_1, \dots, \sigma_D), \ V V^T = I$,

then

$$M^{-1} = V \Sigma^{-1} V^T, \quad \Sigma^{-1} = diag(1/\sigma_1, \dots, 1/\sigma_D),$$

and

$$(M + \lambda I)^{-1} = V\Sigma_{\lambda} = V^{T}, \quad \Sigma_{\lambda} = diag(1/(\sigma_{1} + \lambda), \dots, 1/(\sigma_{D} + \lambda))$$

$$\min_{w \in \mathbb{R}^D} \frac{1}{n} \sum_{i=1}^n (y_i - w^T x_i)^2 + \lambda w^T w, \quad \lambda \ge 0.$$

Statistics?

$$(X_n^T X_n + \lambda nI)w = X_n^T Y_n$$

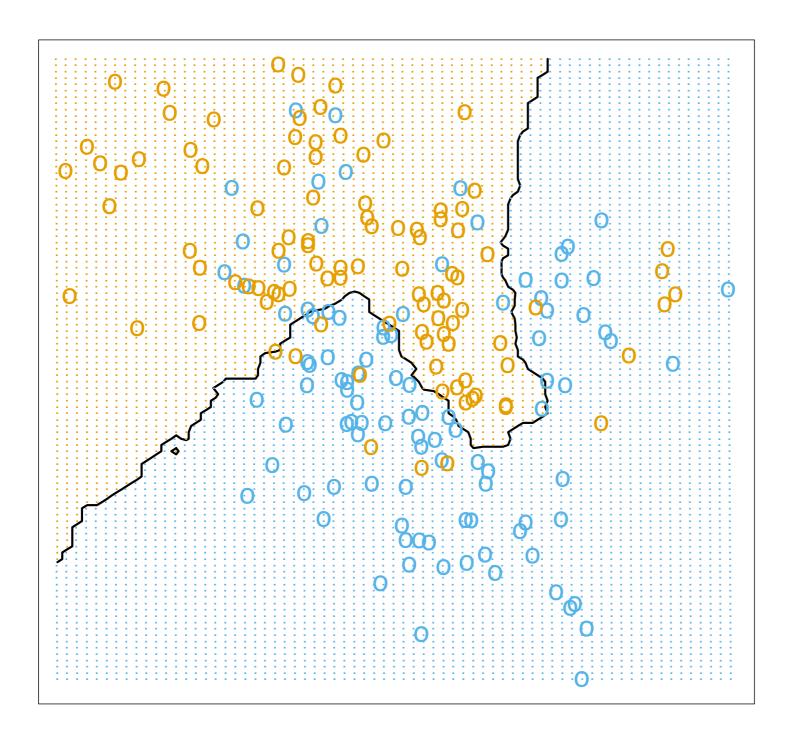
another story that shall be told another time (Stein '56, James and Stein '61)

$$\min_{w \in \mathbb{R}^D} \frac{1}{n} \sum_{i=1}^n (y_i - w^T x_i)^2 + \lambda w^T w, \quad \lambda \ge 0.$$

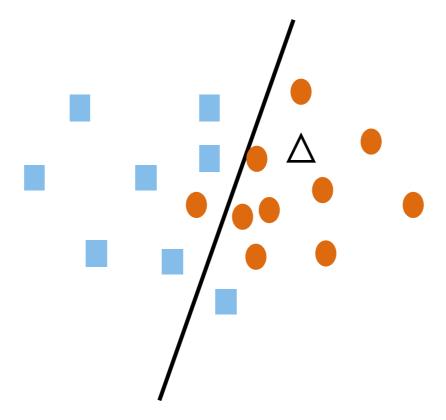
$$f_w(x) = w^T x = \sum_{i=1}^v w^j x^j$$

$$\sum_{j=1}^D (w^j)^2$$

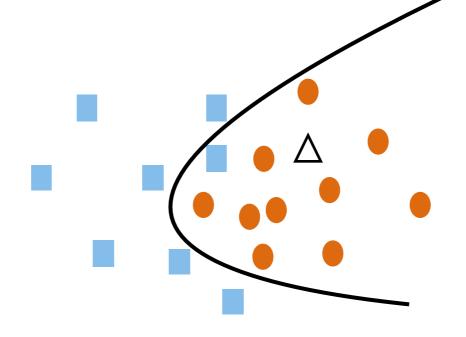
Shrinkage - Stein Effect- Admissible Estimator



Plot



Why a linear decision rule?

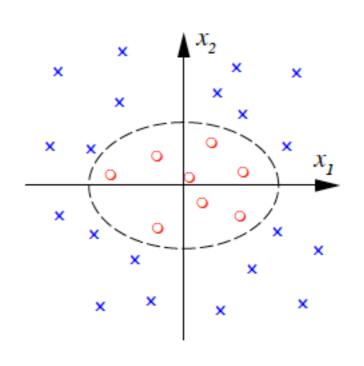


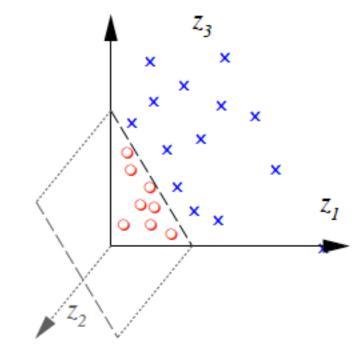
Dictionaries

$$x \mapsto \tilde{x} = (\phi_1(x), \dots, \phi_p(x)) \in \mathbb{R}^p$$

$$f(x) = w^T \tilde{x} = \sum_{j=1}^p \phi_j(x) w^j$$

$$\Phi: R^2 \to R^3$$
 $(x_1, x_2) \mapsto (z_1, z_2, z_3) := (x_1^2, \sqrt{2}x_1x_2, x_2^2)$





$$(X_n^T X_n + \lambda n I)w = X_n^T Y_n \qquad \mapsto \qquad (\tilde{X}_n^T \tilde{X}_n + \lambda n Y)w = \tilde{X}_n^T Y_n$$

What About Computational Complexity?

Complexity Vademecum

M n by p matrix and v, v' p dimensional vectors

- $v^T v' \mapsto O(p)$
- $Mv' \mapsto O(np)$
- $MM^T \mapsto O(n^2p)$
- $\bullet \ (MM^T)^{-1} \mapsto O(n^3)$

$$(X_n^T X_n + \lambda n I)w = X_n^T Y_n \qquad \mapsto \qquad (\tilde{X}_n^T \tilde{X}_n + \lambda n Y)w = \tilde{X}_n^T Y_n$$

What About Computational Complexity?

$$O(p^3) + O(p^2n)$$

What if *p* is much larger than *n*?

$$(X_n^T X_n + \lambda nI)^{-1} X_n^T = X_n^T (X_n X_n^T + \lambda nI)^{-1}$$

$$w = X_n^T \underbrace{(X_n X_n^T + \lambda nI)^{-1} Y_n}_{C} = \sum_{i=1}^n x_i^T c_i$$

$$(X_n^T X_n + \lambda nI)^{-1} X_n^T = X_n^T (X_n X_n^T + \lambda nI)^{-1}$$

$$w = X_n^T \underbrace{(X_n X_n^T + \lambda nI)^{-1} Y_n}_{c} = \sum_{i=1}^n x_i^T c_i$$

Computational Complexity: $O(p^3) + Q(p^2n)$ $O(n^3) + O(pn^2)$

$$O(n^3) + O(pn^2)$$

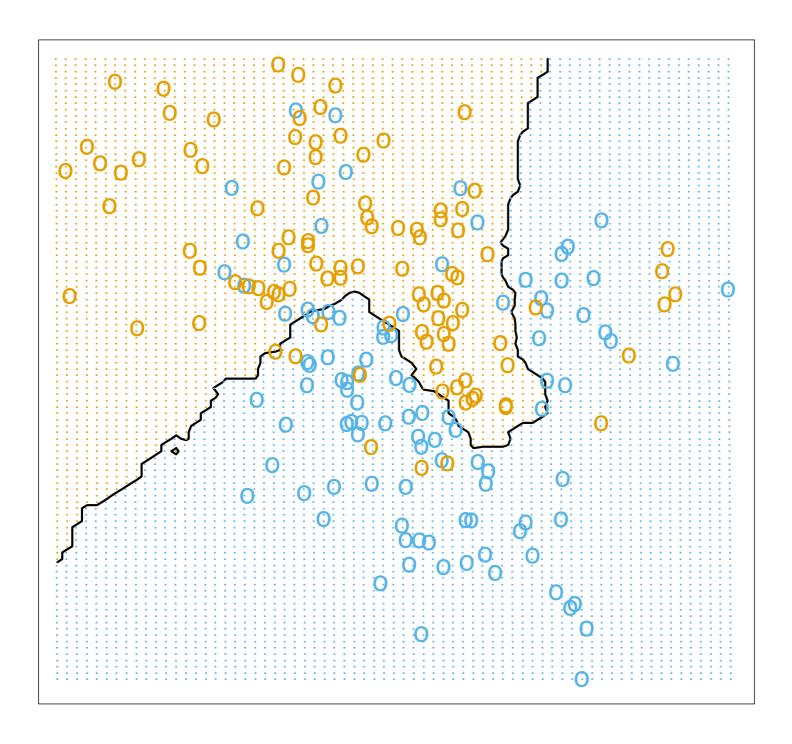
$$(X_n^T X_n + \lambda nI)^{-1} X_n^T = X_n^T (X_n X_n^T + \lambda nI)^{-1}$$

$$w = X_n^T \underbrace{(X_n X_n^T + \lambda nI)^{-1} Y_n}_{c} = \sum_{i=1}^n x_i^T c_i$$

$$w = \sum_{j=1}^{n} x_i c_i \Rightarrow f(x) = x^T w = \sum_{j=1}^{n} \underbrace{x^T x_i}_{K(x, x_i)} c_i$$

$$(K_n + \lambda nI)^{-1}c = Y_n, \quad (K_n)_{i,j} = K(x_i, x_j)$$

- the linear kernel $K(x, x') = x^T x'$,
- the polynomial kernel $K(x, x') = (x^T x' + 1)^d$,
- the Gaussian kernel $K(x, x') = e^{-\frac{\|x x'\|^2}{2\sigma^2}}$,



Plot

$$\hat{f}(x) = \sum_{i=1}^{n} K(x_i, x)c_i.$$

things I won't tell you about

- Reproducing Kernel Hilbert Spaces
- Gaussian Processes
- Integral Equations
- •Sampling Theory/Inverse Problems
- Loss functions- SVM, Logistic...
- Multi task, labels, outputs, classes

End of PART II

- Regularization I: Linear Least Squares
- Regularization II: Kernel Least Squares

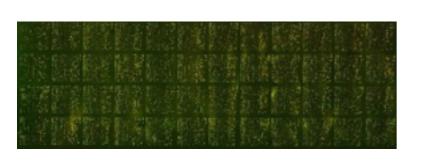
Regularized Least Squares - Dictionaries - Kernels

PART III

- •a) Variable Selection: OMP
- •b) Dimensionality Reduction: PCA

GOAL: To introduce methods that allow to learn *interpretable* models from data

n patients p gene expression measurements



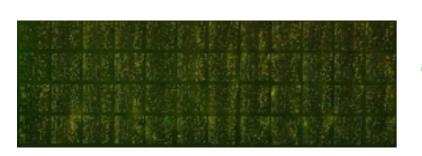
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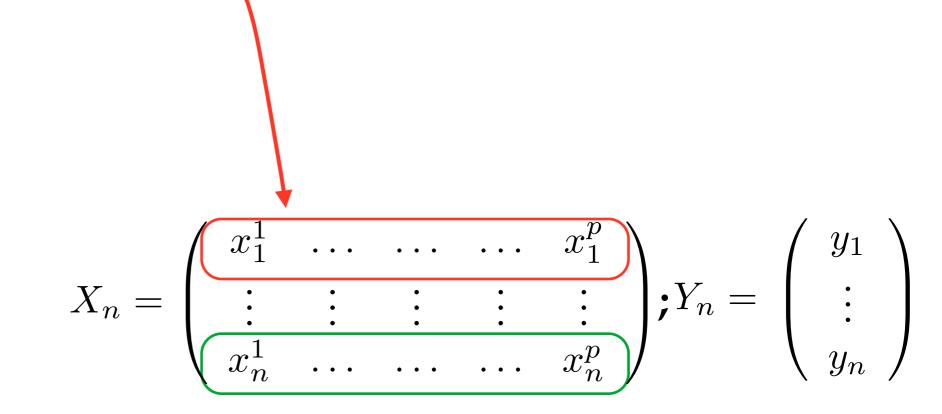


,



• • •





$$f_w(x) = w^T x = \sum_{j=1}^{D} x^j w^j$$

Which variables are important for prediction?

or

Torture the data until they confess

Sparsity: only some of the coefficients are non zero

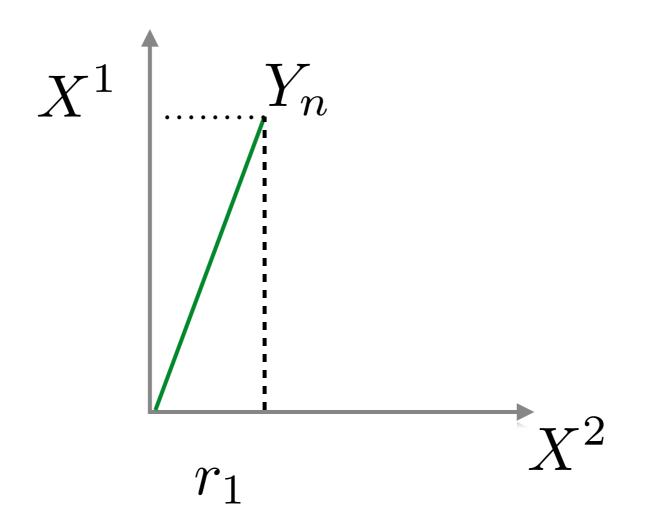
Brute Force Approach

check all individual variables, then all couple, triplets.....

$$\min_{w \in \mathbb{R}^D} \frac{1}{n} \sum_{i=1}^n (y_i - f_w(x_i))^2 + \lambda ||w||_0,$$

$$||w||_0 = |\{j \mid w^j \neq 0\}|$$

Greedy approaches/Matching Pursuit



- (1) initialize the residual, the coefficient vector, and the index set,
- (2) find the variable most correlated with the residual,
- (3) update the index set to include the index of such variable,
- (4) update/compute coefficient vector,
- (5) update residual.

$$r_0 = Y_n, \quad , w_0 = 0, \quad I_0 = \emptyset.$$

Matching Pursuit

(Mallat Zhang '93)

for i = 1, ..., T - 1

$$k = \arg\max_{j=1,...,D} a_j, \quad a_j = \frac{(r_{i-1}^T X^j)^2}{\|X^j\|^2},$$

$$I_i = I_{i-1} \cup \{k\}$$

$$w_i = w_{i-1} + w_k, \quad w_k k = v_k e_k$$

$$r_i = r_{i-1} - Xw^k.$$

end

$$v^{j} = \frac{r_{i-1}^{T} X^{j}}{\|X^{j}\|^{2}} = \arg\min_{v \in \mathbb{R}} \|r_{i-1} - X^{j} v\|^{2}, \quad \|r_{i-1} - X^{j} v^{j}\|^{2} = \|r_{i-1}\|^{2} - a_{j}$$

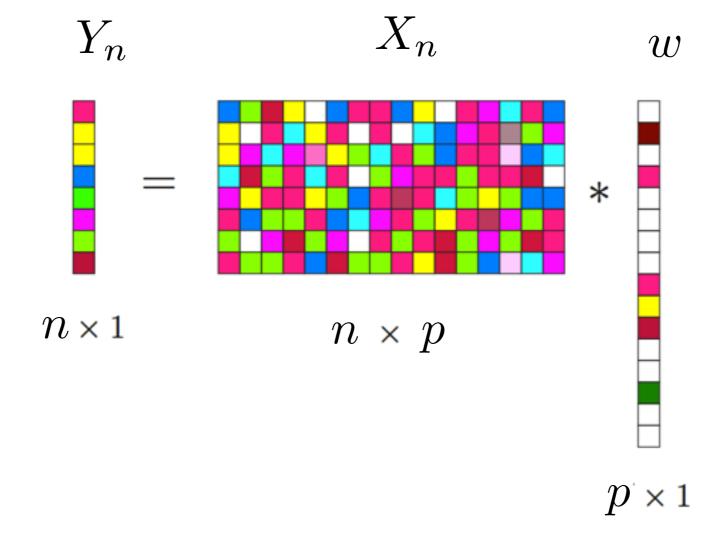
Basis Pursuit/Lasso

(Chen Donoho Saunders ~95, Tibshirani '96)

$$||w||_1 = \sum_{j=1}^{D} |w^j|$$

$$\min_{w \in \mathbb{R}^D} \frac{1}{n} \sum_{i=1}^{n} (y_i - f_w(x_i))^2 + \lambda ||w||_0,$$

Problem is now **convex** and can be solved using convex optimization, in particular so called *proximal methods*



things I won't tell you about

- Solving underdetermined systems
- Sampling theory
- Compressed Sensing
- Structured Sparsity
- From vector to matrices- from sparsity to low rank

End of PART III a)

- •a) Variable Selection: OMP
- •b) Dimensionality Reduction: PCA

Interpretability - Sparsity - Greedy & Convex Relaxation Approaches

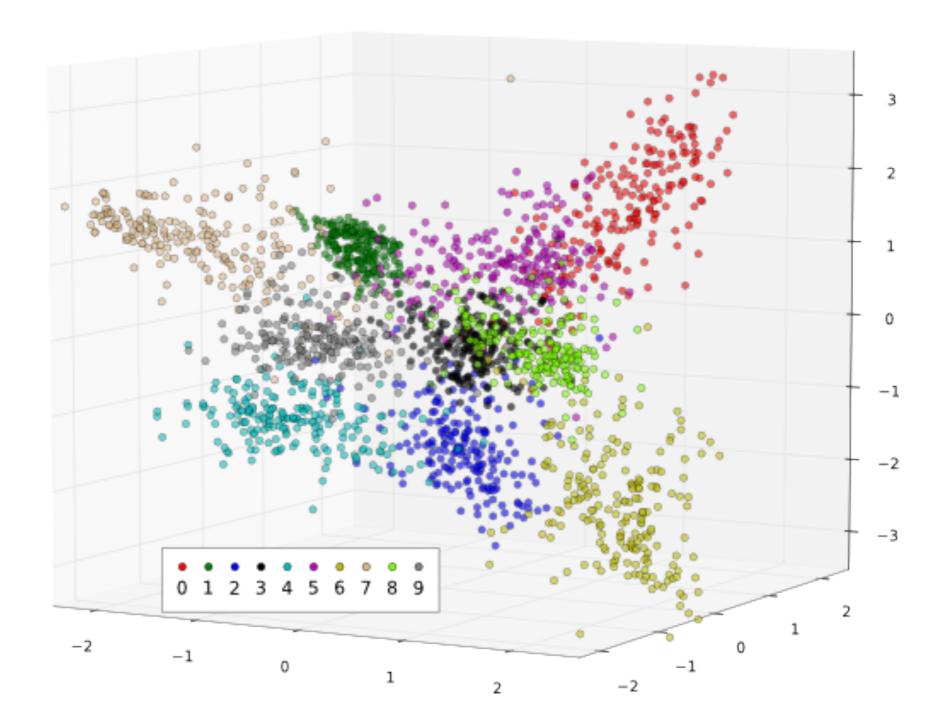
PART III b)

- •a) Variable Selection: OMP
- •b) Dimensionality Reduction: PCA

GOAL: To introduce methods that allow to reduce data dimensionality in absence of labels, namely **unsupervised learning**

Dimensionality Reduction for Data Visualization

```
41571336481976369306
47781372464328614309
17765860039541577321
35257329716946332419
```



$$M: X = \mathbb{R}^D \to \mathbb{R}^k, \quad k \ll D,$$

$$M: X = \mathbb{R}^D \to \mathbb{R}^k, \quad k \ll D,$$

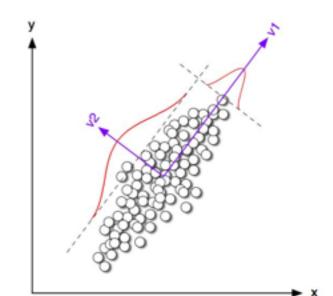
Consider first k = 1

$$M: X = \mathbb{R}^D \to \mathbb{R}^k, \quad k \ll D,$$

Consider first k=1

PCA
$$\min_{w \in \mathbb{S}^{D-1}} \frac{1}{n} \sum_{i=1}^{n} ||x_i - (w^T x_i) w||^2,$$

$$w^T w = 1$$



Computations?

$$\min_{w \in \mathbb{S}^{D-1}} \frac{1}{n} \sum_{i=1}^{n} ||x_i - (w^T x_i) w||^2,$$

$$\min_{w \in \mathbb{S}^{D-1}} \frac{1}{n} \sum_{i=1}^{n} ||x_i - (w^T x_i) w||^2,$$

$$||x_i - (w^T x_i)w||^2 = ||x_i|| - (w^T x_i)^2$$

$$\min_{w \in \mathbb{S}^{D-1}} \frac{1}{n} \sum_{i=1}^{n} ||x_i - (w^T x_i) w||^2,$$

$$||x_i - (w^T x_i)w||^2 = ||x_i|| - (w^T x_i)^2$$

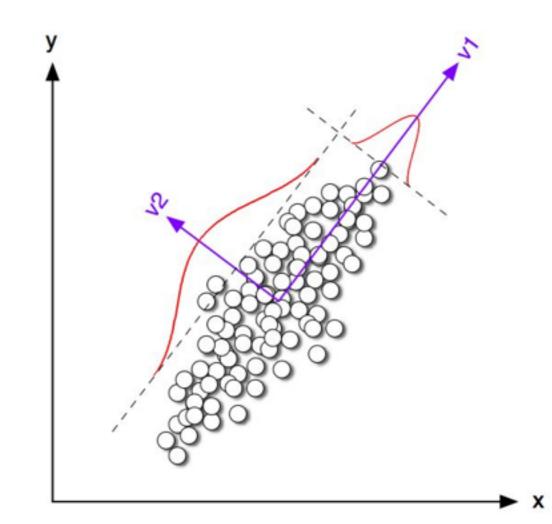
$$\implies \max_{w \in \mathbb{S}^{D-1}} \frac{1}{n} \sum_{i=1}^{n} (w^T x_i)^2.$$

$$\min_{w \in \mathbb{S}^{D-1}} \frac{1}{n} \sum_{i=1}^{n} ||x_i - (w^T x_i) w||^2,$$

$$||x_i - (w^T x_i)w||^2 = ||x_i|| - (w^T x_i)^2$$

$$\implies \max_{w \in \mathbb{S}^{D-1}} \frac{1}{n} \sum_{i=1}^{n} (w^T x_i)^2.$$

$$\implies \max_{w \in \mathbb{S}^{D-1}} \frac{1}{n} \sum_{i=1}^{n} (w^T (x_i - \bar{x}))^2,$$



$$\min_{w \in \mathbb{S}^{D-1}} \frac{1}{n} \sum_{i=1}^{n} ||x_i - (w^T x_i) w||^2,$$

Computations?

$$\min_{w \in \mathbb{S}^{D-1}} \frac{1}{n} \sum_{i=1}^{n} ||x_i - (w^T x_i) w||^2,$$

Computations?

 w_1 max eigenvector of C_n

$$\max_{w \in \mathbb{S}^{D-1}} \frac{1}{n} \sum_{i=1}^{n} (w^{T} x_{i})^{2}. \quad \Leftrightarrow \quad \max_{w \in \mathbb{S}^{D-1}} w^{T} C_{n} w, \quad C_{n} = \frac{1}{n} \sum_{i=1}^{n} x_{i} x_{i}^{T}$$

$$\frac{1}{n} \sum_{i=1}^{n} (w^{T} x_{i})^{2} = \frac{1}{n} \sum_{i=1}^{n} w^{T} x_{i} w^{T} x_{i} = \frac{1}{n} \sum_{i=1}^{n} w^{T} x_{i} x_{i}^{T} w = w^{T} (\frac{1}{n} \sum_{i=1}^{n} x_{i} x_{i}^{T}) w$$

$$M: X = \mathbb{R}^D \to \mathbb{R}^k, \quad k \ll D,$$

What about k = 2?

• • •

 w_2 second eigenvector of C_n

$$\max_{\substack{w \in \mathbb{S}^{D-1} \\ w \perp w_1}} w^T C_n w, \quad C_n = \frac{1}{n} \sum_{i=1}^n x_i x_i^T.$$

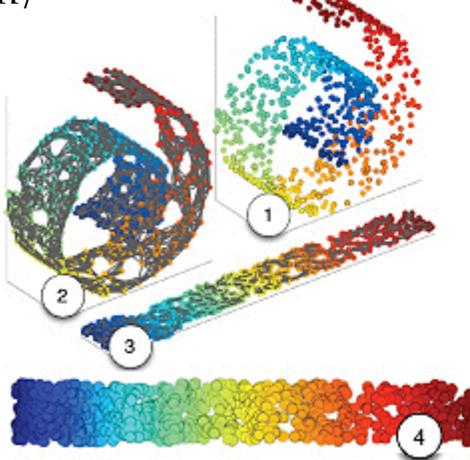
$$M: X = \mathbb{R}^D \to \mathbb{R}^k, \quad k \ll D,$$

things I won't tell you about

• Random Maps: Johnson-Linderstrauss Lemma

•Non Linear Maps: Kernel PCA, Laplacian/

Diffusion maps



End of PART III b)

- •a) Variable Selection: OMP
- •b) Dimensionality Reduction: PCA

Interpretability - Sparsity - Greedy & Convex Relaxation Approaches

The End



PART IV

Matlab practical session

Afternoon