

## Exercises - Larry Abbott, June 10

1. Simulate the model

$$\frac{dx_i}{dt} = -x_i + g \sum_{j=1}^N J_{ij} \tanh(x_j) \quad (1)$$

for  $i = 1, 2, \dots, N$  with each element  $J_{ij}$  chosen independently from a Gaussian distribution with zero mean and variance  $1/N$ . Take  $N = 1000$ , and examine what happens for values of  $g$  in the range from 0.5 to 2. Initialize  $x_i$  for  $i = 1, 2, \dots, N$  randomly in a reasonable range. Compare with reference 1, below.

2. Extend the model in (1), with  $g = 1.5$ , by adding an external input, so that

$$\frac{dx_i}{dt} = -x_i + g \sum_{j=1}^N J_{ij} \tanh(x_j) + u_i A \cos(\omega t) \quad (2)$$

with  $u_i$ , for  $i = 1, 2, \dots, N$ , chosen independently from a uniform distribution ranging from  $-1$  to  $1$ . Look at what happens to the activity as a function of  $A$  and  $\omega$ . Compare with reference 2, below.

3. Extend the model in (1), with  $g = 1.5$ , by adding a term

$$\frac{dx_i}{dt} = -x_i + g \sum_{j=1}^N J_{ij} \tanh(x_j) + u_i z \quad (3)$$

with  $u_i$  chosen as in (2), and

$$z = \sum_{i=1}^N w_i \tanh(x_i). \quad (4)$$

Adjust the weights  $w_i$ , for  $i = 1, 2, \dots, N$ , so that  $z$  matches a target function

$$f = \cos\left(\frac{2\pi t}{50}\right). \quad (5)$$

Set the initial weights randomly from a uniform distribution ranging from  $-1/\sqrt{N}$  to  $1/\sqrt{N}$ . Also, initialize an  $N \times N$  matrix with elements  $P_{ij}$ , for  $i, j = 1, 2, \dots, N$ , to  $P_{ij} = 0$  if  $i \neq j$  and  $P_{ii} = 1$  for all  $i$ . Then, adjust the weights by applying the FORCE learning rule, for all  $i$ ,

$$w_i \rightarrow w_i + c(f - z)q_i, \quad (6)$$

where

$$q_i = \sum_{j=1}^N P_{ij} \tanh(x_j) \quad (7)$$

and

$$c = \frac{1}{1 + \sum_i q_i \tanh(x_i)}. \quad (8)$$

Finally, update the matrix  $P$  by

$$P_{ij} \rightarrow P_{ij} - cq_i q_j. \quad (9)$$

After a while, stop the weight adjustment and the network should produce  $z = f$  autonomously. If this works, feel free to try more complex functions  $f(t)$ . For comparison, see reference 3.

4. Build a network of integrate-and-fire model neurons, satisfying

$$\tau_m \frac{dV_i}{dt} = V_{\text{rest}} - V_i + I_0 + s_i \quad (10)$$

for  $i = 1, 2, \dots, N$ , with  $N = 1000$ ,  $\tau_m = 20$  ms,  $I_0 = 11$  mV and  $V_{\text{rest}} = -60$  mV. The neuron spikes when  $V_i$  reaches a threshold value  $V_{\text{th}} = -50$  mV and then is reset to  $V_{\text{reset}} = -60$  mV. Following a spike,  $V_i$  is clamped to  $V_i = V_{\text{rest}}$  for 5 ms. Finally,  $V_i$  is not allowed to fall below  $-80$  mV. In other words, following an update using the above equation, if  $V_i < -80$ ,  $V_i$  is set to  $-80$ .

The synaptic current  $s_i$  satisfies the equation

$$\tau_s \frac{ds_i}{dt} = -s_i \quad (11)$$

for all  $i$  with  $\tau_s = 10$  ms. When some neuron  $j$  fires a spike,  $s_i$ , for all  $i = 1, 2, \dots, N$  except  $i = j$ , is updated by

$$s_i \rightarrow s_i + \mu + gJ_{ij} \quad (12)$$

with  $g = 3$  mV,  $\mu = -0.5$  mV, and all the elements  $J_{ij}$  chosen independently from a Gaussian distribution with zero mean and variance 1. Initialize  $V_i$  for  $i = 1, 2, \dots, N$  randomly, see what happens and then do whatever you want with the model.

5. If you have the energy, construct the model in reference 4.

## References

- 1) H. Sompolinsky, A. Crisanti, and H. J. Sommers (1988) Phys. Rev. Lett. 61, 259.
- 2) K. Rajan, L.R. Abbott and H. Sompolinsky (2010) Phys. Rev. E 82:011903.
- 3) D. Sussillo and L.F. Abbott, (2009) Neuron 63:544-557.
- 4) M, Boerlin, C.K. Machens and S. Deneve (2013) PLoS Comput Biol. 9:e1003258.