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Double descent in the condition number

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Abstract

In solving a system of n linear equations in d variables $Ax = b$, the condition number of the n, d matrix A measures how much errors in the data b affect the solution x . Bounds of this type are important in many inverse problems. An example is machine learning where the key task is to estimate an underlying function from a set of measurements at random points in a high dimensional space and where low sensitivity to error in the data is a requirement for good predictive performance. Here we discuss the simple observation, which is well-known but surprisingly little quoted, that when the columns of A are random vectors, the condition number of A is highest if $d = n$, that is when the inverse of A exists. An overdetermined system ($n > d$) as well as an underdetermined system ($n < d$), for which the pseudoinverse must be used instead of the inverse, typically have significantly better, that is lower, condition numbers. Thus the condition number of A plotted as function of d shows a double descent behavior with a peak at $d = n$.



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In solving a system of n linear equations in d variables $Ax = b$, the condition number of the n, d matrix A measures how much errors in the data b affect the solution x . Bounds of this type are important in many inverse problems. An example is machine learning where the key task is to estimate an underlying function from a set of measurements at random points in a high dimensional space and where low sensitivity to error in the data is a requirement for good predictive performance. Here we discuss the simple observation, which is well-known but surprisingly little quoted (see Theorem 4.2 in [1]) that when the columns of A are random vectors, the condition number of A is highest if $d = n$, that is when the inverse of A exists. An overdetermined system ($n > d$) as well as an underdetermined system ($n < d$), for which the pseudoinverse must be used instead of the inverse, typically have significantly better, that is lower, condition numbers. Thus the condition number of A plotted as function of d shows a double descent behavior with a peak at $d = n$.

The concept of condition number was introduced by Turing in 1948 [2] and has since played a key role in the theory of algorithms. The condition number of a function measures how much the output value of the function can change for a small change in the input argument. The condition number most commonly associated with $Ax = b$ is defined as the ratio of the relative error in x to the relative error in the data b . In terms of the l_2 norm on x and b , this leads to the following definition for the condition number of A , denoted by $\kappa(A) = \|A\| \|A^\dagger\|$ with $\|A\|$ being the operator norm of the m, n matrix A and A^\dagger the pseudoinverse. The operator norm is defined as $\|A\| = \sup_x \|Ax\|$ with $\|x\| = 1$. It is easy to see that $\kappa(A) = \frac{\sigma_{\max}(A)}{\sigma_{\min}(A)}$ is the ratio of the maximal and minimal singular values of A .

The plot in the Figure 1 can be easily checked by calling the function “cond” in MatLab. The double descent pattern is apparently quite robust to choices of d and n , such that their ratio $\gamma = \frac{n}{d}$ is the same. The fact that the worse conditioning occurs when the inverse exists uniquely ($\gamma = 1$) seems at first surprising. This simple observation must have been realized by many. The proof is also simple because of a well-known characterization of the eigenvalues of random matrices [3]. In fact, consider the n, d random matrix A . We characterize its condition number by using the Marchenko–Pastur law, which describes the asymptotic behavior of singular values of large rectangular random matrices. We assume that the entries of A are independent, identically distributed random variables with mean 0 and variance σ^2 . We consider the limit

for $n \rightarrow \infty$ with $\frac{n}{d} \rightarrow \gamma$. Marchenko–Pastur claims that for $\gamma < 1$ the smallest and the largest singular values of $\frac{1}{d}AA^T$ are, respectively $(1 - \sqrt{\gamma})^2$ and $(1 + \sqrt{\gamma})^2$. For $\gamma > 1$ the largest and the smallest eigenvalues of $\frac{1}{n}A^T A$ are $(1 + \sqrt{\gamma^{-1}})^2$ and $(1 - \sqrt{\gamma^{-1}})^2$. When $\gamma = 1$, and the entries are i.i.d. sub-Gaussian, the maximal singular value is concentrated around 2, but the minimal one is $\min\{n^{-1}, d^{-1}\}(\max\{\sqrt{n} - \sqrt{d-1}, \sqrt{d} - \sqrt{n-1}\})^2$, as was observed in [4].

For the system of linear equations $Ax = b$, the implication is that is better to have more variables than data: the condition number associated with the minimum norm solution $x = A^\dagger b$ is usually much better – that is closer to 1 – than the condition number of a well-determined system with $n = d$, if the matrix A is random (see for instance [5]).

There are interesting observations for machine learning. The most obvious is that kernel methods, which are a popular workhorse in machine learning, *do not require regularization in order to be well-conditioned*, if the kernel matrices are based on high dimensional i.i.d data, especially when $\gamma < 1$. This claim follows from recent results on kernels. The simplest form of the kernel matrix $K(x_j, x_i)$ is $K = XX^T$. We consider random matrices whose entries are $K(x_i^T x_j)$ with i.i.d. vectors x_i in \mathbb{R}^p with normalized distribution (in Figure 2 we consider a radial kernel $K(\|x_i - x_j\|^2)$ for which similar arguments are likely to hold). Assuming that f is sufficiently smooth and the distribution of x_i 's is sufficiently nice, El Karoui [6] showed that the spectral distributions of kernel dot-product matrices $K(x_i, x_j) = f(\frac{1}{d}XX^T)$ behave as if f is linear in the Marchenko–Pastur limit. In fact, El Karoui showed that under mild conditions, the kernel matrix is asymptotically equivalent to a linear combination of XX^T , the all-1's matrix, and the identity, and hence the limiting spectrum is Marcenko-Pastur. As a consequence, the claims about the condition number of a random matrix A also apply to kernel matrices with random data, see Figure 2.

More intriguing is the fact that the behavior of the condition number of K^\dagger is similar to the *double descent* behavior of the test error by linear and kernel interpolants, which after pioneering work by Belkin ([7], see also [8]) has recently attracted much attention [9, 10, 7, 11, 12, 13, 14]. We will address the key role of stability, discussed in some detail in previous versions of this memo, in a separate paper currently in preparation.

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Author Contribution All developed the basic theory.

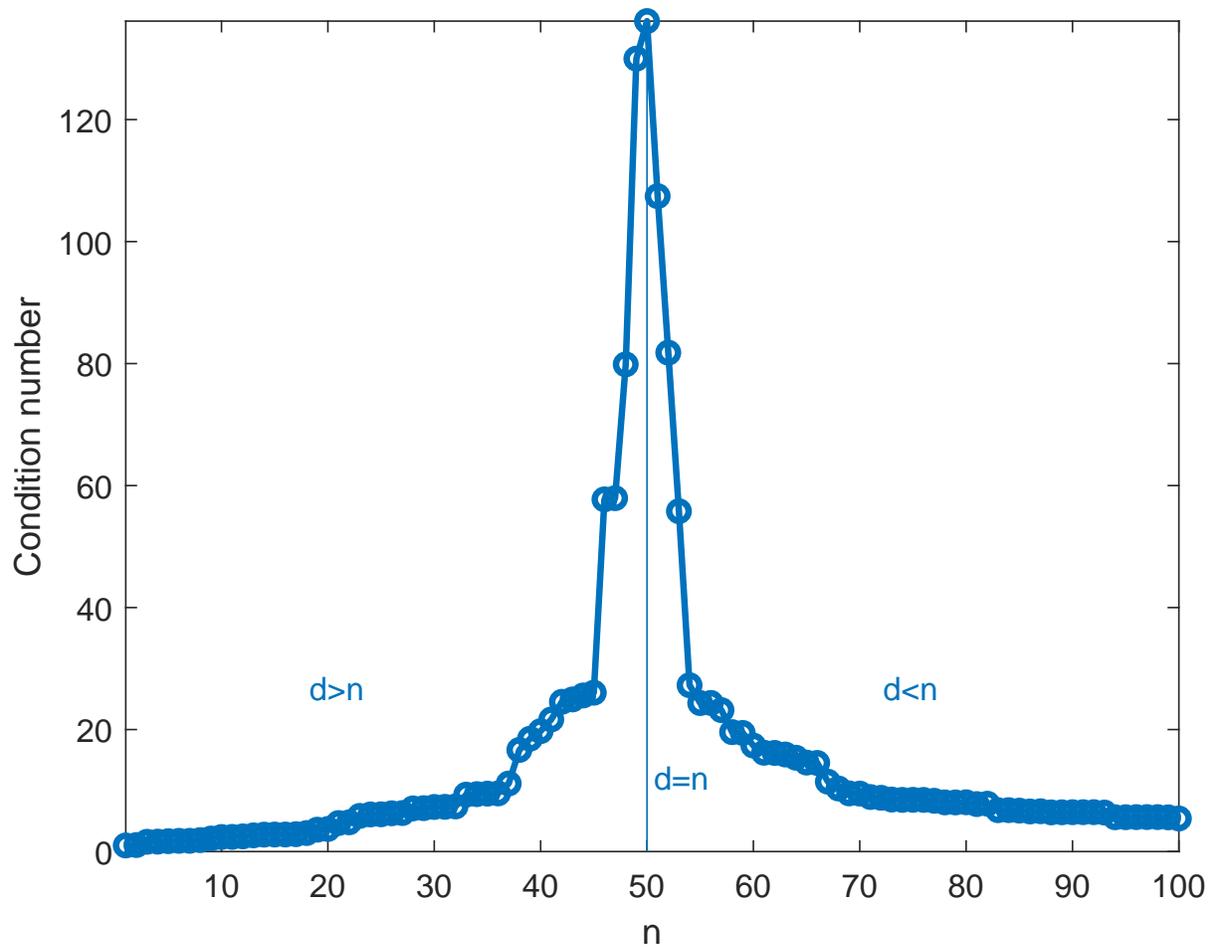


Figure 1: Typical double descent of the condition number (y axis) of a random data matrix distributed as $\mathcal{N}(0, 1)$: the condition number is worse when $n = d$, better if $n > d$ (on the right of $n = d$) and also better if $n < d$ (on the left of $n = d$).

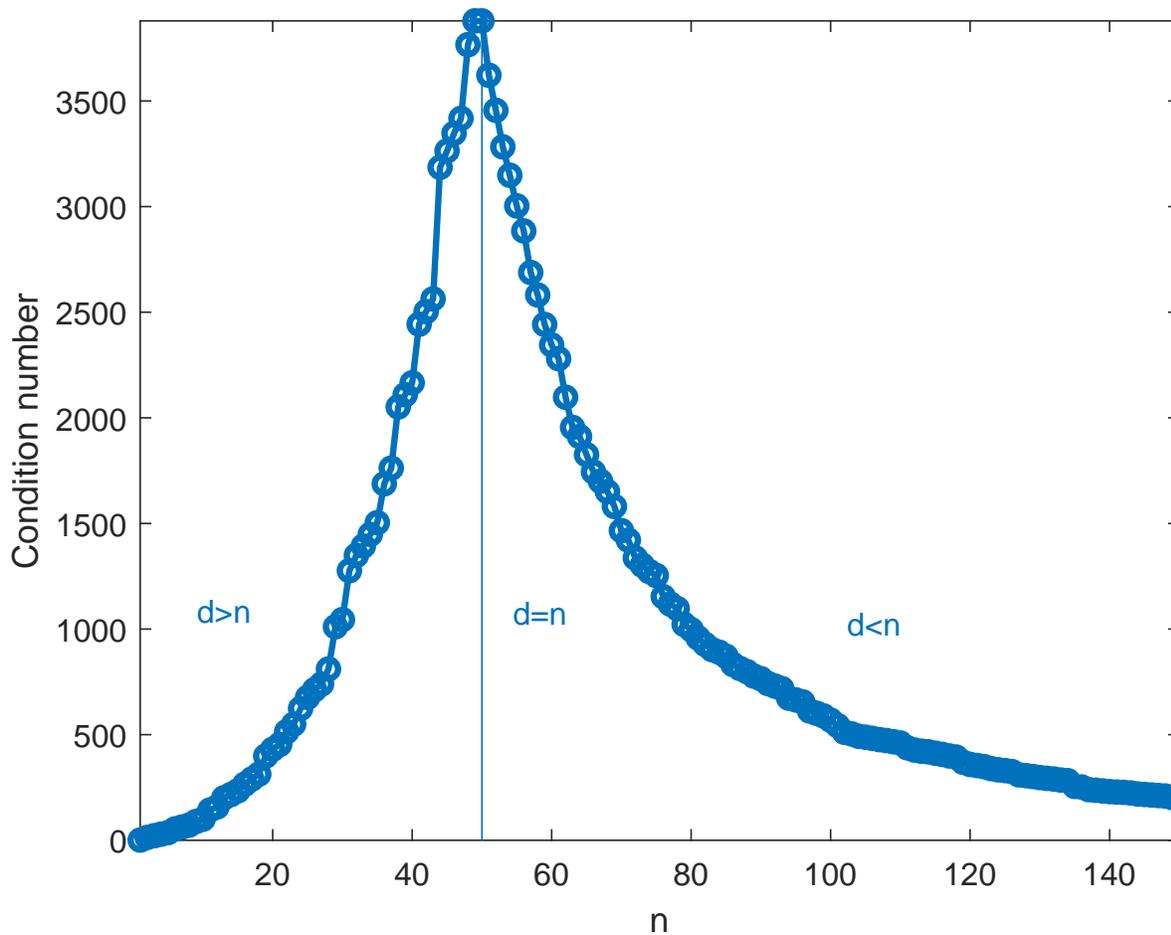


Figure 2: Typical double descent of the condition number (y axis) of a radial basis function kernel $K(x, x') = \exp\left(-\frac{\|x-x'\|^2}{2\sigma^2}\right)$ built from a random data matrix distributed as $\mathcal{N}(0, 1)$: as in the linear case, the condition number is worse when $n = d$, better if $n > d$ (on the right of $n = d$) and also better if $n < d$ (on the left of $n = d$). The parameter σ was chosen to be 5.

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